# **NAG Library Function Document**

# nag\_zhpsvx (f07ppc)

## 1 Purpose

nag\_zhpsvx (f07ppc) uses the diagonal pivoting factorization

$$A = UDU^{\mathrm{H}}$$
 or  $A = LDL^{\mathrm{H}}$ 

to compute the solution to a complex system of linear equations

AX = B,

where A is an n by n Hermitian matrix stored in packed format and X and B are n by r matrices. Error bounds on the solution and a condition estimate are also provided.

## 2 Specification

```
#include <nag.h>
#include <nagf07.h>
void nag_zhpsvx (Nag_OrderType order, Nag_FactoredFormType fact,
    Nag_UploType uplo, Integer n, Integer nrhs, const Complex ap[],
    Complex afp[], Integer ipiv[], const Complex b[], Integer pdb,
    Complex x[], Integer pdx, double *rcond, double ferr[], double berr[],
    NagError *fail)
```

## **3** Description

nag\_zhpsvx (f07ppc) performs the following steps:

- 1. If fact = Nag\_NotFactored, the diagonal pivoting method is used to factor A as  $A = UDU^{H}$  if uplo = Nag\_Upper or  $A = LDL^{H}$  if uplo = Nag\_Lower, where U (or L) is a product of permutation and unit upper (lower) triangular matrices and D is Hermitian and block diagonal with 1 by 1 and 2 by 2 diagonal blocks.
- 2. If some  $d_{ii} = 0$ , so that *D* is exactly singular, then the function returns with **fail.errnum** = *i* and **fail.code** = NE\_SINGULAR. Otherwise, the factored form of *A* is used to estimate the condition number of the matrix *A*. If the reciprocal of the condition number is less than *machine precision*, **fail.code** = NE\_SINGULAR\_WP is returned as a warning, but the function still goes on to solve for *X* and compute error bounds as described below.
- 3. The system of equations is solved for X using the factored form of A.
- 4. Iterative refinement is applied to improve the computed solution matrix and to calculate error bounds and backward error estimates for it.

## 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D (1999) *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia http://www.netlib.org/lapack/lug

Golub G H and Van Loan C F (1996) Matrix Computations (3rd Edition) Johns Hopkins University Press, Baltimore

Higham N J (2002) Accuracy and Stability of Numerical Algorithms (2nd Edition) SIAM, Philadelphia

### 5 Arguments order – Nag OrderType 1: Input On entry: the order argument specifies the two-dimensional storage scheme being used, i.e., rowmajor ordering or column-major ordering. C language defined storage is specified by $order = Nag_RowMajor$ . See Section 2.3.1.3 in How to Use the NAG Library and its Documentation for a more detailed explanation of the use of this argument. *Constraint*: **order** = Nag\_RowMajor or Nag\_ColMajor. fact - Nag FactoredFormType Input 2: On entry: specifies whether or not the factorized form of the matrix A has been supplied. fact = Nag\_Factored afp and ipiv contain the factorized form of the matrix A. afp and ipiv will not be modified. **fact** = Nag\_NotFactored The matrix A will be copied to **afp** and factorized. *Constraint*: **fact** = Nag\_Factored or Nag\_NotFactored. uplo – Nag UploType 3: Input On entry: if $uplo = Nag_Upper$ , the upper triangle of A is stored. If uplo = Nag.Lower, the lower triangle of A is stored. *Constraint*: **uplo** = Nag\_Upper or Nag\_Lower. 4: n – Integer Input On entry: n, the number of linear equations, i.e., the order of the matrix A. *Constraint*: $\mathbf{n} \geq 0$ . 5: nrhs – Integer Input On entry: r, the number of right-hand sides, i.e., the number of columns of the matrix B. Constraint: $\mathbf{nrhs} \geq 0$ . ap[dim] - const ComplexInput 6: Note: the dimension, *dim*, of the array **ap** must be at least $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$ . On entry: the n by n Hermitian matrix A, packed by rows or columns. The storage of elements $A_{ij}$ depends on the **order** and **uplo** arguments as follows: if **order** = Nag\_ColMajor and **uplo** = Nag\_Upper, $A_{ii}$ is stored in $\mathbf{ap}[(j-1) \times j/2 + i - 1]$ , for $i \leq j$ ; if order = Nag\_ColMajor and uplo = Nag\_Lower, $A_{ij}$ is stored in $\mathbf{ap}[(2n-j) \times (j-1)/2 + i - 1]$ , for $i \ge j$ ; if order = Nag\_RowMajor and uplo = Nag\_Upper, $A_{ij}$ is stored in $\operatorname{ap}[(2n-i) \times (i-1)/2 + j - 1]$ , for $i \leq j$ ; if **order** = Nag\_RowMajor and **uplo** = Nag\_Lower, $A_{ij}$ is stored in $\mathbf{ap}[(i-1) \times i/2 + j - 1]$ , for $i \ge j$ .

### 7: $\mathbf{afp}[dim] - \mathbf{Complex}$

Note: the dimension, dim, of the array afp must be at least  $\max(1, \mathbf{n} \times (\mathbf{n} + 1)/2)$ .

Input/Output

On entry: if  $fact = Nag_Factored$ , afp contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization  $A = UDU^{H}$  or  $A = LDL^{H}$  as computed by nag zhptrf (f07prc), stored as a packed triangular matrix in the same storage format as A.

On exit: if  $fact = Nag_NotFactored$ , afp contains the block diagonal matrix D and the multipliers used to obtain the factor U or L from the factorization  $A = UDU^{H}$  or  $A = LDL^{H}$  as computed by nag zhptrf (f07prc), stored as a packed triangular matrix in the same storage format as A.

#### **ipiv**[**n**] – Integer 8:

On entry: if fact = Nag-Factored, ipiv contains details of the interchanges and the block structure of D, as determined by nag zhptrf (f07prc).

if ipiv[i-1] = k > 0,  $d_{ii}$  is a 1 by 1 pivot block and the *i*th row and column of A were interchanged with the kth row and column;

if **uplo** = Nag\_Upper and **ipiv**[i-2] = ipiv[i-1] = -l < 0,  $\begin{pmatrix} d_{i-1,i-1} & \overline{d}_{i,i-1} \\ \overline{d}_{i,i-1} & d_{ii} \end{pmatrix}$  is a 2 by 2 pivot block and the (i-1)th row and column of A were interchanged with the *l*th row and column;

if **uplo** = Nag\_Lower and **ipiv**[i-1] = ipiv[i] = -m < 0,  $\begin{pmatrix} d_{ii} & d_{i+1,i} \\ d_{i+1,i} & d_{i+1,i+1} \end{pmatrix}$  is a 2 by 2 pivot block and the (i+1)th row and column of A were interchanged with the mth row

and column.

On exit: if  $fact = Nag_NotFactored$ , ipiv contains details of the interchanges and the block structure of D, as determined by nag zhptrf (f07prc), as described above.

#### $\mathbf{b}[dim]$ – const Complex 9:

Note: the dimension, dim, of the array b must be at least

 $\max(1, \mathbf{pdb} \times \mathbf{nrhs})$  when  $\mathbf{order} = \operatorname{Nag-ColMajor}$ ;  $\max(1, \mathbf{n} \times \mathbf{pdb})$  when  $\mathbf{order} = \operatorname{Nag}_{\operatorname{Row}} \operatorname{Major}$ .

The (i, j)th element of the matrix B is stored in

 $\mathbf{b}[(j-1) \times \mathbf{pdb} + i - 1]$  when  $\mathbf{order} = \text{Nag_ColMajor};$  $\mathbf{b}[(i-1) \times \mathbf{pdb} + j - 1]$  when  $\mathbf{order} = \text{Nag_RowMajor}.$ 

On entry: the n by r right-hand side matrix B.

#### pdb – Integer 10:

On entry: the stride separating row or column elements (depending on the value of order) in the array **b**.

Constraints:

if order = Nag\_ColMajor,  $pdb \ge max(1, n)$ ; if order = Nag\_RowMajor, pdb > max(1, nrhs).

 $\mathbf{x}[dim] - Complex$ 11:

Note: the dimension, dim, of the array x must be at least

 $\max(1, \mathbf{pdx} \times \mathbf{nrhs})$  when  $\mathbf{order} = \operatorname{Nag-ColMajor}$ ;  $\max(1, \mathbf{n} \times \mathbf{pdx})$  when  $\mathbf{order} = \operatorname{Nag}_{\operatorname{Row}} \operatorname{Major}_{\operatorname{r}}$ .

The (i, j)th element of the matrix X is stored in

 $\mathbf{x}[(j-1) \times \mathbf{pdx} + i - 1]$  when order = Nag\_ColMajor;  $\mathbf{x}[(i-1) \times \mathbf{pdx} + j - 1]$  when order = Nag\_RowMajor.

On exit: if fail.code = NE NOERROR or NE SINGULAR WP, the n by r solution matrix X.

Input/Output

f07ppc.3

Output

Input

Input

#### 12: **pdx** – Integer

On entry: the stride separating row or column elements (depending on the value of **order**) in the array  $\mathbf{x}$ .

Constraints:

if order = Nag\_ColMajor,  $pdx \ge max(1, n)$ ; if order = Nag\_RowMajor,  $pdx \ge max(1, nrhs)$ .

#### 13: rcond – double \*

On exit: the estimate of the reciprocal condition number of the matrix A. If rcond = 0.0, the matrix may be exactly singular. This condition is indicated by fail.code = NE\_SINGULAR. Otherwise, if rcond is less than the *machine precision*, the matrix is singular to working precision. This condition is indicated by fail.code = NE\_SINGULAR\_WP.

### 14: $\mathbf{ferr}[\mathbf{nrhs}] - \mathbf{double}$

On exit: if fail.code = NE\_NOERROR or NE\_SINGULAR\_WP, an estimate of the forward error bound for each computed solution vector, such that  $\|\hat{x}_j - x_j\|_{\infty} / \|x_j\|_{\infty} \leq \operatorname{ferr}[j-1]$  where  $\hat{x}_j$  is the *j*th column of the computed solution returned in the array **x** and  $x_j$  is the corresponding column of the exact solution X. The estimate is as reliable as the estimate for rcond, and is almost always a slight overestimate of the true error.

### 15: **berr**[**nrhs**] – double

On exit: if fail.code = NE\_NOERROR or NE\_SINGULAR\_WP, an estimate of the componentwise relative backward error of each computed solution vector  $\hat{x}_j$  (i.e., the smallest relative change in any element of A or B that makes  $\hat{x}_j$  an exact solution).

#### 16: **fail** – NagError \*

The NAG error argument (see Section 2.7 in How to Use the NAG Library and its Documentation).

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

See Section 3.2.1.2 in How to Use the NAG Library and its Documentation for further information.

### NE\_BAD\_PARAM

On entry, argument  $\langle value \rangle$  had an illegal value.

### NE\_INT

On entry,  $\mathbf{n} = \langle value \rangle$ . Constraint:  $\mathbf{n} \ge 0$ .

On entry,  $\mathbf{nrhs} = \langle value \rangle$ . Constraint:  $\mathbf{nrhs} \ge 0$ .

On entry,  $\mathbf{pdb} = \langle value \rangle$ . Constraint:  $\mathbf{pdb} > 0$ .

On entry,  $\mathbf{pdx} = \langle value \rangle$ . Constraint:  $\mathbf{pdx} > 0$ . Input/Output

Output

Output

Output

On entry,  $\mathbf{pdb} = \langle value \rangle$  and  $\mathbf{n} = \langle value \rangle$ . Constraint:  $\mathbf{pdb} \geq \max(1, \mathbf{n})$ .

On entry,  $\mathbf{pdb} = \langle value \rangle$  and  $\mathbf{nrhs} = \langle value \rangle$ . Constraint:  $\mathbf{pdb} \geq \max(1, \mathbf{nrhs})$ .

On entry,  $\mathbf{pdx} = \langle value \rangle$  and  $\mathbf{n} = \langle value \rangle$ . Constraint:  $\mathbf{pdx} \ge \max(1, \mathbf{n})$ .

On entry,  $\mathbf{pdx} = \langle value \rangle$  and  $\mathbf{nrhs} = \langle value \rangle$ . Constraint:  $\mathbf{pdx} \ge \max(1, \mathbf{nrhs})$ .

#### NE\_INTERNAL\_ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG. See Section 3.6.6 in How to Use the NAG Library and its Documentation for further information.

#### NE\_NO\_LICENCE

Your licence key may have expired or may not have been installed correctly. See Section 3.6.5 in How to Use the NAG Library and its Documentation for further information.

#### NE\_SINGULAR

Element  $\langle value \rangle$  of the diagonal is exactly zero. The factorization has been completed, but the factor D is exactly singular, so the solution and error bounds could not be computed. **rcond** = 0.0 is returned.

#### NE\_SINGULAR\_WP

D is nonsingular, but **rcond** is less than *machine precision*, meaning that the matrix is singular to working precision. Nevertheless, the solution and error bounds are computed because there are a number of situations where the computed solution can be more accurate than the value of **rcond** would suggest.

### 7 Accuracy

For each right-hand side vector b, the computed solution  $\hat{x}$  is the exact solution of a perturbed system of equations  $(A + E)\hat{x} = b$ , where

$$||E||_1 = O(\epsilon) ||A||_1,$$

where  $\epsilon$  is the *machine precision*. See Chapter 11 of Higham (2002) for further details.

If  $\hat{x}$  is the true solution, then the computed solution x satisfies a forward error bound of the form

$$\frac{\|x - \hat{x}\|_{\infty}}{\|\hat{x}\|_{\infty}} \le w_c \operatorname{cond}(A, \hat{x}, b)$$

where  $\operatorname{cond}(A, \hat{x}, b) = \||A^{-1}|(|A||\hat{x}| + |b|)\|_{\infty}/\|\hat{x}\|_{\infty} \leq \operatorname{cond}(A) = \||A^{-1}||A|\|_{\infty} \leq \kappa_{\infty}(A)$ . If  $\hat{x}$  is the *j*th column of X, then  $w_c$  is returned in **berr**[j-1] and a bound on  $\|x - \hat{x}\|_{\infty}/\|\hat{x}\|_{\infty}$  is returned in **ferr**[j-1]. See Section 4.4 of Anderson *et al.* (1999) for further details.

#### 8 Parallelism and Performance

nag\_zhpsvx (f07ppc) is threaded by NAG for parallel execution in multithreaded implementations of the NAG Library.

nag\_zhpsvx (f07ppc) makes calls to BLAS and/or LAPACK routines, which may be threaded within the vendor library used by this implementation. Consult the documentation for the vendor library for further information.

Please consult the x06 Chapter Introduction for information on how to control and interrogate the OpenMP environment used within this function. Please also consult the Users' Notefor your implementation for any additional implementation-specific information.

## 9 Further Comments

The factorization of A requires approximately  $\frac{4}{3}n^3$  floating-point operations.

For each right-hand side, computation of the backward error involves a minimum of  $16n^2$  floating-point operations. Each step of iterative refinement involves an additional  $24n^2$  operations. At most five steps of iterative refinement are performed, but usually only one or two steps are required. Estimating the forward error involves solving a number of systems of equations of the form Ax = b; the number is usually 4 or 5 and never more than 11. Each solution involves approximately  $8n^2$  operations.

The real analogue of this function is nag\_dspsvx (f07pbc). The complex symmetric analogue of this function is nag\_zspsvx (f07qpc).

## 10 Example

This example solves the equations

$$AX = B,$$

where A is the Hermitian matrix

$$A = \begin{pmatrix} -1.84 & 0.11 - 0.11i & -1.78 - 1.18i & 3.91 - 1.50i \\ 0.11 + 0.11i & -4.63 & -1.84 + 0.03i & 2.21 + 0.21i \\ -1.78 + 1.18i & -1.84 - 0.03i & -8.87 & 1.58 - 0.90i \\ 3.91 + 1.50i & 2.21 - 0.21i & 1.58 + 0.90i & -1.36 \end{pmatrix}$$

and

$$B = \begin{pmatrix} 2.98 - 10.18i & 28.68 - 39.89i \\ -9.58 + 3.88i & -24.79 - 8.40i \\ -0.77 - 16.05i & 4.23 - 70.02i \\ 7.79 + 5.48i & -35.39 + 18.01i \end{pmatrix}.$$

Error estimates for the solutions, and an estimate of the reciprocal of the condition number of the matrix A are also output.

### 10.1 Program Text

```
double rcond;
 Integer exit_status = 0, i, j, n, nrhs, pdb, pdx;
  /* Arrays */
 Complex *afp = 0, *ap = 0, *b = 0, *x = 0;
 double *berr = 0, *ferr = 0;
 Integer *ipiv = 0;
 char nag_enum_arg[40];
 /* Nag Types */
 NagError fail;
 Nag_OrderType order;
 Nag_UploType uplo;
#ifdef NAG_COLUMN_MAJOR
#define A_UPPER(I, J) ap[J*(J-1)/2 + I - 1]
order = Nag_ColMajor;
#else
#define A_LOWER(I, J) ap[I*(I-1)/2 + J - 1]
#define A_UPPER(I, J) ap[(2*n-I)*(I-1)/2 + J - 1]
                    b[(I-1)*pdb + J - 1]
#define B(I, J)
 order = Nag_RowMajor;
#endif
 INIT_FAIL(fail);
 printf("naq_zhpsvx (f07ppc) Example Program Results\n\n");
  /* Skip heading in data file */
#ifdef WIN32
 scanf_s("%*[^\n]");
#else
 scanf("%*[^\n]");
#endif
#ifdef _WIN32
 scanf_s("%" NAG_IFMT "%" NAG_IFMT "%*[^\n]", &n, &nrhs);
#else
 scanf("%" NAG_IFMT "%" NAG_IFMT "%*[^\n]", &n, &nrhs);
#endif
 if (n < 0 || nrhs < 0) {
   printf("Invalid n or nrhs\n");
   exit_status = 1;
   goto END;
 }
#ifdef _WIN32
 scanf_s(" %39s%*[^\n]", nag_enum_arg, (unsigned)_countof(nag_enum_arg));
#else
 scanf(" %39s%*[^\n]", nag_enum_arg);
#endif
 /* nag_enum_name_to_value (x04nac).
  * Converts NAG enum member name to value
  */
 uplo = (Nag_UploType) nag_enum_name_to_value(nag_enum_arg);
  /* Allocate memory */
 if (!(afp = NAG_ALLOC(n * (n + 1) / 2, Complex)) ||
     !(ap = NAG_ALLOC(n * (n + 1) / 2, Complex)) ||
     !(b = NAG_ALLOC(n * nrhs, Complex)) ||
     !(x = NAG_ALLOC(n * nrhs, Complex)) ||
     !(berr = NAG_ALLOC(nrhs, double)) ||
     !(ferr = NAG_ALLOC(nrhs, double)) || !(ipiv = NAG_ALLOC(n, Integer)))
  {
   printf("Allocation failure\n");
   exit_status = -1;
   goto END;
#ifdef NAG_COLUMN_MAJOR
 pdb = n;
```

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```
pdx = n;
#else
 pdb = nrhs;
 pdx = nrhs;
#endif
  /* Read the triangular part of the matrix A from data file */
  if (uplo == Nag_Upper)
    for (i = 1; i <= n; ++i)
     for (j = i; j <= n; ++j)</pre>
#ifdef _WIN32
        scanf_s(" ( %lf , %lf )", &A_UPPER(i, j).re, &A_UPPER(i, j).im);
#else
        scanf(" ( %lf , %lf )", &A_UPPER(i, j).re, &A_UPPER(i, j).im);
#endif
 else if (uplo == Nag_Lower)
    for (i = 1; i <= n; ++i)
     for (j = 1; j <= i; ++j)
#ifdef _WIN32
        scanf_s(" ( %lf , %lf )", &A_LOWER(i, j).re, &A_LOWER(i, j).im);
#else
        scanf(" ( %lf , %lf )", &A_LOWER(i, j).re, &A_LOWER(i, j).im);
#endif
#ifdef _WIN32
 scanf_s("%*[^\n]");
#else
 scanf("%*[^\n]");
#endif
  /* Read B from data file */
 for (i = 1; i <= n; ++i)
   for (j = 1; j <= nrhs; ++j)</pre>
#ifdef _WIN32
     scanf_s(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#else
      scanf(" ( %lf , %lf )", &B(i, j).re, &B(i, j).im);
#endif
#ifdef _WIN32
 scanf_s("%*[^\n]");
#else
 scanf("%*[^\n]");
#endif
  /* Solve the equations AX = B for X using nag_zhpsvx (f07ppc). */
 nag_zhpsvx(order, Nag_NotFactored, uplo, n, nrhs, ap, afp, ipiv, b, pdb, x,
             pdx, &rcond, ferr, berr, &fail);
  if (fail.code != NE_NOERROR && fail.code != NE_SINGULAR) {
    printf("Error from nag_zhpsvx (f07ppc).\n%s\n", fail.message);
    exit_status = 1;
    goto END;
 }
  /* Print solution using nag_gen_complx_mat_print_comp (x04dbc). */
 fflush(stdout);
 nag_gen_complx_mat_print_comp(order, Nag_GeneralMatrix, Nag_NonUnitDiag, n,
                                 nrhs, x, pdx, Nag_BracketForm, "%7.4f",
                                 "Solution(s)", Nag_IntegerLabels, 0,
                                Nag_IntegerLabels, 0, 80, 0, 0, &fail);
 if (fail.code != NE_NOERROR) {
   printf("Error from nag_gen_complx_mat_print_comp (x04dbc).\n%s\n",
           fail.message);
    exit_status = 1;
    goto END;
 }
  /* Print error bounds and condition number */
 printf("\nBackward errors (machine-dependent)\n");
 for (j = 0; j < nrhs; ++j)
   printf("%11.1e%s", berr[j], j % 7 == 6 ? "\n" : " ");
 printf("\n\nEstimated forward error bounds (machine-dependent)\n");
```

```
for (j = 0; j < nrhs; ++j)
   printf("%11.1e%s", ferr[j], j % 7 == 6 ? "\n" : " ");
  printf("\n\nEstimate of reciprocal condition number\n%11.1e\n", rcond);
  if (fail.code == NE_SINGULAR) {
   printf("Error from nag_zhpsvx (f07ppc).\n%s\n", fail.message);
   exit_status = 1;
  }
END:
  NAG_FREE(afp);
  NAG_FREE(ap);
  NAG_FREE(b);
  NAG_FREE(x);
 NAG_FREE(berr);
 NAG_FREE(ferr);
 NAG_FREE(ipiv);
 return exit_status;
}
#undef A_UPPER
#undef A_LOWER
#undef B
```

#### **10.2 Program Data**

### **10.3 Program Results**

nag\_zhpsvx (f07ppc) Example Program Results Solution(s) 1 ( 2.0000, 1.0000) (-8.0000, 6.0000) 2 ( 3.0000,-2.0000) ( 7.0000,-2.0000) 3 (-1.0000, 2.0000) (-1.0000, 5.0000) 4 ( 1.0000,-1.0000) ( 3.0000,-4.0000) Backward errors (machine-dependent) 5.1e-17 5.9e-17 Estimated forward error bounds (machine-dependent) 2.5e-15 3.0e-15 Estimate of reciprocal condition number 1.5e-01