

## NAG Library Function Document

### **nag\_tsa\_resid\_corr (g13asc)**

## 1 Purpose

nag\_tsa\_resid\_corr (g13asc) is a diagnostic checking function suitable for use after fitting a Box–Jenkins ARMA model to a univariate time series using nag\_tsa\_multi\_inp\_model\_estim (g13bec). The residual autocorrelation function is returned along with an estimate of its asymptotic standard errors and correlations. Also, nag\_tsa\_resid\_corr (g13asc) calculates the Box–Ljung portmanteau statistic and its significance level for testing model adequacy.

## 2 Specification

```
#include <nag.h>
#include <nagg13.h>
void nag_tsa_resid_corr (Nag_ArimaOrder *arimav, Integer n, const double v[],
                         Integer m, const double par[], Integer narma, double r[], double rc[],
                         Integer tdrc, double *chi, Integer *df, double *siglev, NagError *fail)
```

## 3 Description

Consider the univariate multiplicative autoregressive-moving average model

$$\phi(B)\Phi(B^s)(W_t - \mu) = \theta(B)\Theta(B^s)\epsilon_t \quad (1)$$

where  $W_t$ , for  $t = 1, 2, \dots, n$ , denotes a time series and  $\epsilon_t$ , for  $t = 1, 2, \dots, n$ , is a residual series assumed to be Normally distributed with zero mean and variance  $\sigma^2 (> 0)$ . The  $\epsilon_t$ 's are also assumed to be uncorrelated. Here  $\mu$  is the overall mean term,  $s$  is the seasonal period and  $B$  is the backward shift operator such that  $B^r W_t = W_{t-r}$ . The polynomials in (1) are defined as follows:

$$\phi(B) = 1 - \phi_1 B - \phi_2 B^2 - \dots - \phi_p B^p$$

is the non-seasonal autoregressive (AR) operator;

$$\theta(B) = 1 - \theta_1 B - \theta_2 B^2 - \dots - \theta_q B^q$$

is the non-seasonal moving average (MA) operator;

$$\Phi(B^s) = 1 - \Phi_1 B^s - \Phi_2 B^{2s} - \dots - \Phi_P B^{Ps}$$

is the seasonal AR operator; and

$$\Theta(B^s) = 1 - \Theta_1 B^s - \Theta_2 B^{2s} - \dots - \Theta_Q B^{Qs}$$

is the seasonal MA operator. The model (1) is assumed to be stationary, that is the zeros of  $\phi(B)$  and  $\Phi(B^s)$  are assumed to lie outside the unit circle. The model (1) is also assumed to be invertible, that is the zeros of  $\theta(B)$  and  $\Theta(B^s)$  are assumed to lie outside the unit circle. When both  $\Phi(B^s)$  and  $\Theta(B^s)$  are absent from the model, that is when  $P = Q = 0$ , then the model is said to be non-seasonal.

The estimated residual autocorrelation coefficient at lag  $l$ ,  $\hat{r}_l$ , is computed as:

$$\hat{r}_l = \frac{\sum_{t=l+1}^n (\hat{\epsilon}_{t-l} - \bar{\epsilon})(\hat{\epsilon}_t - \bar{\epsilon})}{\sum_{t=1}^n (\hat{\epsilon}_t - \bar{\epsilon})^2}, \quad l = 1, 2, \dots$$

where  $\hat{\epsilon}_t$  denotes an estimate of the  $t$ th residual,  $\epsilon_t$ , and  $\bar{\epsilon} = \sum_{t=1}^n \hat{\epsilon}_t / n$ . A portmanteau statistic,  $Q_{(m)}$ , is calculated from the formula (see Box and Ljung (1978)):

$$Q_{(m)} = n(n+2) \sum_{l=1}^m \hat{r}_l^2 / (n-l)$$

where  $m$  denotes the number of residual autocorrelations computed. (Advice on the choice of  $m$  is given in Section 9.) Under the hypothesis of model adequacy,  $Q_{(m)}$  has an asymptotic  $\chi^2$  distribution on  $m - p - q - P - Q$  degrees of freedom. Let  $\hat{r}^T = (\hat{r}_1, \hat{r}_2, \dots, \hat{r}_m)$  then the variance-covariance matrix of  $\hat{r}$  is given by:

$$\text{Var}(\hat{r}) = [I_m - X(X^T X)^{-1} X^T] / n.$$

The construction of the matrix  $X$  is discussed in McLeod (1978). (Note that the mean,  $\mu$ , and the residual variance,  $\sigma^2$ , play no part in calculating  $\text{Var}(\hat{r})$  and therefore are not required as input to nag\_tsa\_resid\_corr (g13asc).)

## 4 References

Box G E P and Ljung G M (1978) On a measure of lack of fit in time series models *Biometrika* **65** 297–303

McLeod A I (1978) On the distribution of the residual autocorrelations in Box–Jenkins models *J. Roy. Statist. Soc. Ser. B* **40** 296–302

## 5 Arguments

1: **arimav** – Nag\_ArimaOrder \*

Pointer to structure of type Nag\_ArimaOrder with the following members:

<b>p</b> – Integer	
<b>d</b> – Integer	<i>Input</i>
<b>q</b> – Integer	<i>Input</i>
<b>bigp</b> – Integer	<i>Input</i>
<b>bigd</b> – Integer	<i>Input</i>
<b>bigq</b> – Integer	<i>Input</i>
<b>s</b> – Integer	<i>Input</i>

*On entry:* these seven members of **arimav** must specify the orders vector  $(p, d, q, P, D, Q, s)$ , respectively, of the ARIMA model for the output noise component.

$p$ ,  $q$ ,  $P$  and  $Q$  refer, respectively, to the number of autoregressive ( $\phi$ ), moving average ( $\theta$ ), seasonal autoregressive ( $\Phi$ ) and seasonal moving average ( $\Theta$ ) arguments.

$d$ ,  $D$  and  $s$  refer, respectively, to the order of non-seasonal differencing, the order of seasonal differencing and the seasonal period.

*Constraints:*

$$\begin{aligned} \text{arimav}\rightarrow\mathbf{p}, \text{arimav}\rightarrow\mathbf{q}, \text{arimav}\rightarrow\mathbf{bigp}, \text{arimav}\rightarrow\mathbf{bigq}, \text{arimav}\rightarrow\mathbf{s} &\geq 0, \\ \text{arimav}\rightarrow\mathbf{p} + \text{arimav}\rightarrow\mathbf{q} + \text{arimav}\rightarrow\mathbf{bigp} + \text{arimav}\rightarrow\mathbf{bigq} &> 0, \\ \text{if } \text{arimav}\rightarrow\mathbf{s} = 0, \text{ then } \text{arimav}\rightarrow\mathbf{bigp} &= 0 \text{ and } \text{arimav}\rightarrow\mathbf{bigq} = 0. \end{aligned}$$

2: **n** – Integer

*Input*

*On entry:* the number of observations in the residual series,  $n$ .

*Constraint:*  $\mathbf{n} \geq 3$ .

3:	<b>v[n]</b> – const double	<i>Input</i>
<i>On entry:</i> <b>v[t – 1]</b> must contain an estimate of $\epsilon_t$ , for $t = 1, 2, \dots, n$ .		
<i>Constraint:</i> <b>v</b> must contain at least two distinct elements.		
4:	<b>m</b> – Integer	<i>Input</i>
<i>On entry:</i> the value of $m$ , the number of residual autocorrelations to be computed. See Section 9 for advice on the value of <b>m</b> .		
<i>Constraint:</i> <b>narma &lt; m &lt; n</b> .		
5:	<b>par[narma]</b> – const double	<i>Input</i>
<i>On entry:</i> the parameter estimates in the order $\phi_1, \phi_2, \dots, \phi_p, \theta_1, \theta_2, \dots, \theta_q, \Phi_1, \Phi_2, \dots, \Phi_P, \Theta_1, \Theta_2, \dots, \Theta_Q$ only.		
<i>Constraint:</i> the elements in <b>par</b> must satisfy the stationarity and invertibility conditions.		
6:	<b>narma</b> – Integer	<i>Input</i>
<i>On entry:</i> the number of ARMA arguments, $\phi, \theta, \Phi$ and $\Theta$ arguments, i.e., <b>narma</b> = $p + q + P + Q$ .		
<i>Constraint:</i> <b>narma = arimav→p + arimav→q + arimav→bigp + arimav→bigq</b> .		
7:	<b>r[m]</b> – double	<i>Output</i>
<i>On exit:</i> an estimate of the residual autocorrelation coefficient at lag $l$ , for $l = 1, 2, \dots, m$ . If <b>fail.code</b> = NE_G13AS_ZERO_VAR on exit then all elements of <b>r</b> are set to zero.		
8:	<b>rc[m × tdrc]</b> – double	<i>Output</i>
<i>On exit:</i> the estimated standard errors and correlations of the elements in the array <b>r</b> . The correlation between <b>r[i – 1]</b> and <b>r[j – 1]</b> is returned as <b>rc[(i – 1) × tdrc + j – 1]</b> except that if $i = j$ then <b>rc[(i – 1) × tdrc + j – 1]</b> contains the standard error of <b>r[i – 1]</b> . If on exit, <b>fail.code</b> = NE_G13AS_FACT or NE_G13AS_DIAG, then all off-diagonal elements of <b>rc</b> are set to zero and all diagonal elements are set to $1/\sqrt{n}$ .		
9:	<b>tdrc</b> – Integer	<i>Input</i>
<i>On entry:</i> the stride separating matrix column elements in the array <b>rc</b> .		
<i>Constraint:</i> <b>tdrc ≥ m</b> .		
10:	<b>chi</b> – double *	<i>Output</i>
<i>On exit:</i> the value of the portmanteau statistic, $Q_{(m)}$ . If <b>fail.code</b> = NE_G13AS_ZERO_VAR on exit then <b>chi</b> is returned as zero.		
11:	<b>df</b> – Integer *	<i>Output</i>
<i>On exit:</i> the number of degrees of freedom of <b>chi</b> .		
12:	<b>siglev</b> – double *	<i>Output</i>
<i>On exit:</i> the significance level of <b>chi</b> based on <b>df</b> degrees of freedom. If <b>fail.code</b> = NE_G13AS_ZERO_VAR on exit then <b>siglev</b> is returned as one.		
13:	<b>fail</b> – NagError *	<i>Input/Output</i>
The NAG error argument (see Section 3.6 in the Essential Introduction).		

## 6 Error Indicators and Warnings

### **NE\_2\_INT\_ARG\_LT**

On entry, **tdrc** =  $\langle value \rangle$  while **m** =  $\langle value \rangle$ . These arguments must satisfy  $\text{tdrc} \geq \text{m}$ .

### **NE\_ALLOC\_FAIL**

Dynamic memory allocation failed.

### **NE\_ARIMA\_INPUT**

On entry, **arimav**→**p** =  $\langle value \rangle$ , **arimav**→**d** =  $\langle value \rangle$ , **arimav**→**q** =  $\langle value \rangle$ , **arimav**→**bigp** =  $\langle value \rangle$ , **arimav**→**bigd** =  $\langle value \rangle$ , **arimav**→**bigq** =  $\langle value \rangle$  and **arimav**→**s** =  $\langle value \rangle$ .

Constraints on the members of **arimav** are:

**arimav**→**p**,    **arimav**→**q**,    **arimav**→**bigp**,    **arimav**→**bigq**,    **arimav**→**s**  $\geq 0$ ,  
**arimav**→**p** + **arimav**→**q** + **arimav**→**bigp** + **arimav**→**bigq**  $> 0$ , if **arimav**→**s** = 0, then  
**arimav**→**bigp** = 0 and **arimav**→**bigq** = 0.

### **NE\_G13AS\_AR**

On entry, the autoregressive (or moving average) arguments are extremely close to or outside the stationarity (or invertibility) region. To proceed, you must supply different parameter estimates in the array **par**.

### **NE\_G13AS\_DIAG**

This is an unlikely exit. At least one of the diagonal elements of **rc** was found to be either negative or zero. In this case all off-diagonal elements of **rc** are returned as zero and all diagonal elements of **rc** set to  $1/\sqrt{(n)}$ .

### **NE\_G13AS\_FACT**

On entry, one or more of the AR operators has a factor in common with one or more of the MA operators. To proceed, this common factor must be deleted from the model. In this case, the off-diagonal elements of **rc** are returned as zero and the diagonal elements set to  $1/\sqrt{(n)}$ . All other output quantities will be correct.

### **NE\_G13AS\_ITER**

This is an unlikely exit brought about by an excessive number of iterations being needed to evaluate the zeros of the AR or MA polynomials. All output arguments are undefined.

### **NE\_G13AS\_ZERO\_VAR**

On entry, the residuals are practically identical giving zero (or near zero) variance. In this case **chi** is set to zero, **siglev** to one and all the elements of **r** set to zero.

### **NE\_INPUT\_NARMA**

On entry, **arimav**→**p** =  $\langle value \rangle$ , **arimav**→**q** =  $\langle value \rangle$ , **arimav**→**bigp** =  $\langle value \rangle$ , **arimav**→**bigq** =  $\langle value \rangle$  while **narma** =  $\langle value \rangle$ .

Constraint: **narma** = **arimav**→**p** + **arimav**→**q** + **arimav**→**bigp** + **arimav**→**bigq**.

### **NE\_INT\_3**

On entry, **m** =  $\langle value \rangle$ , **n** =  $\langle value \rangle$ , **narma** =  $\langle value \rangle$ .

Constraint: **narma** < **m** < **n**.

**NE\_INT\_ARG\_LT**

On entry, **n** =  $\langle \text{value} \rangle$ .  
 Constraint: **n**  $\geq 3$ .

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

**7 Accuracy**

The computations are believed to be stable.

**8 Parallelism and Performance**

Not applicable.

**9 Further Comments****9.1 Timing**

The time taken by nag\_tsa\_resid\_corr (g13asc) depends upon the number of residual autocorrelations to be computed,  $m$ .

**9.2 Choice of  $m$** 

The number of residual autocorrelations to be computed,  $m$  should be chosen to ensure that when the ARMA model (1) is written as either an infinite order autoregressive process:

$$W_t - \mu = \sum_{j=1}^{\infty} \pi_j (W_{t-j} - \mu) + \epsilon_t$$

or as an infinite order moving average process:

$$W_t - \mu = \sum_{j=1}^{\infty} \psi_j \epsilon_{t-j} + \epsilon_t$$

then the two sequences  $\{\pi_1, \pi_2, \dots\}$  and  $\{\psi_1, \psi_2, \dots\}$  are such that  $\pi_j$  and  $\psi_j$  are approximately zero for  $j > m$ . An overestimate of  $m$  is therefore preferable to an under-estimate of  $m$ . In many instances the choice  $m = 10$  will suffice. In practice, to be on the safe side, you should try setting  $m = 20$ .

**9.3 Approximate Standard Errors**

When **fail.code** = NE\_G13AS\_FACT or NE\_G13AS\_DIAG all the standard errors in **rc** are set to  $1/\sqrt{n}$ . This is the asymptotic standard error of  $\hat{r}_l$  when all the autoregressive and moving average arguments are assumed to be known rather than estimated.

**10 Example**

A program to fit an ARIMA(1,1,2) model to a series of 30 observations. 10 residual autocorrelations are computed.

## 10.1 Program Text

```

/* nag_tsa_resid_corr (g13asc) Example Program.
*
* Copyright 2014 Numerical Algorithms Group.
*
* Mark 6, 2000.
*/
#include <stdio.h>
#include <string.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagg13.h>

int main(void)
{
    Integer          exit_status = 0, i, idf, j, m, *mr = 0, narma, ni, npar;
    Integer          nres, nseries, nx;
    NagError         fail;
    Nag_ArimaOrder   arimav;
    Nag_G13_Opt      options;
    Nag_TransfOrder  transfv;
    double           chi, df, objf, *par = 0, *r = 0, *rc = 0, *res, s, *sd = 0,
                    siglev, *x = 0;

    INIT_FAIL(fail);

    printf("nag_tsa_resid_corr (g13asc) Example Program Results\n\n");

    /* Skip heading in data file */
#ifndef _WIN32
    scanf_s("%*[^\n]");
#else
    scanf("%*[^\n]");
#endif

#ifndef _WIN32
    scanf_s("%"NAG_IFMT"%*[^\n]", &nx);
#else
    scanf("%"NAG_IFMT"%*[^\n]", &nx);
#endif
    if (!(x = NAG_ALLOC(nx, double))
        || !(mr = NAG_ALLOC(7, Integer)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }

    for (i = 1; i <= nx; ++i)
#ifndef _WIN32
        scanf_s("%lf", &x[i - 1]);
#else
        scanf("%lf", &x[i - 1]);
#endif
#ifndef _WIN32
        scanf_s("%*[^\n]");
#else
        scanf("%*[^\n]");
#endif
        for (i = 1; i <= 7; ++i)
#ifndef _WIN32
            scanf_s("%"NAG_IFMT"", &mr[i - 1]);
#else
            scanf("%"NAG_IFMT"", &mr[i - 1]);
#endif
#ifndef _WIN32
            scanf_s("%*[^\n]");
#else
            scanf("%*[^\n]");
#endif

```

```
#endif

npar = mr[0] + mr[2] + mr[3] + mr[5] + 1;
if (!(par = NAG_ALLOC(npar, double))
    || !(sd = NAG_ALLOC(npar, double)))
{
    printf("Allocation failure\n");
    exit_status = -1;
    goto END;
}
for (i = 1; i <= npar; ++i)
    par[i - 1] = 0.0;

nseries = 1;
arimav.p = mr[0];
arimav.d = mr[1];
arimav.q = mr[2];
arimav.bigp = mr[3];
arimav.bigd = mr[4];
arimav.biggq = mr[5];
arimav.s = mr[6];
/* nag_tsa_options_init (g13bc).
 * Initialization function for option setting
 */
nag_tsa_options_init(&options);
/* nag_tsa_transf_orders (g13byc).
 * Allocates memory to transfer function model orders
 */
nag_tsa_transf_orders(nseries, &transfv, &fail);
/* nag_tsa_multi_inp_model_estim (g13bec).
 * Estimation for time series models
 */
fflush(stdout);
nag_tsa_multi_inp_model_estim(&arimav, nseries, &transfv, par, npar, nx, x,
                                nseries, sd, &s, &objf, &df, &options, &fail);
nres = options.lenres;
res = options.res;
if (fail.code != NE_NOERROR)
{
    printf(
        "Error from nag_tsa_multi_inp_model_estim (g13bec).\n%s\n",
        fail.message);
    exit_status = 1;
    goto END;
}

m = 10;
if (!(r = NAG_ALLOC(m, double))
    || !(rc = NAG_ALLOC(m*m, double)))
{
    printf("Allocation failure\n");
    exit_status = -1;
    goto END;
}

narma = mr[0] + mr[2] + mr[3] + mr[5];
/* nag_tsa_resid_corr (g13asc).
 * Univariate time series, diagnostic checking of residuals,
 * following nag_tsa_multi_inp_model_estim (g13bec)
 */
nag_tsa_resid_corr(&arimav, nres, res, m, par, narma, r, rc,
                    m, &chi, &idf, &siglev, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_tsa_resid_corr (g13asc).\n%s\n",
          fail.message);
    exit_status = 1;
    goto END;
}
printf("\nRESIDUAL AUTOCORRELATION FUNCTION");
printf("\n-----\n\n");
```

```

for (j = 0; j <= (m-1)/7; j++)
{
    ni = MIN(7, m - j*7);
    printf("LAG K ");
    for (i = 0; i < ni; i++)
        printf("%5" NAG_IFMT" ", i+j*7+1);
    printf("\nR(K) ");
    for (i = 0; i < ni; i++)
        printf("%7.3f", r[i+j*7]);
    printf("\nST.ERROR");
    for (i = 0; i < ni; i++)
        printf("%7.3f", rc[(m+1)*(i+j*7)]);
    printf(
        "\n-----\n");
}
/* nag_tsa_free (g13xzc).
 * Freeing function for use with g13 option setting
 */
nag_tsa_free(&options);

END:
NAG_FREE(x);
NAG_FREE(mr);
NAG_FREE(par);
NAG_FREE(sd);
NAG_FREE(r);
NAG_FREE(rc);
return exit_status;
}

```

## 10.2 Program Data

```

nag_tsa_resid_corr (g13asc) Example Program Data
30          : nx, length of the time series
-217 -177 -166 -136 -110  -95  -64  -37
-14   -25  -51  -62  -73  -88  -113 -120
-83  -33  -19   21   17   44   44   78
  88  122  126  114   85   64      : End of time series
1  1  2  0  0  0  0 : mr, orders vector of the model

```

## 10.3 Program Results

```
nag_tsa_resid_corr (g13asc) Example Program Results
```

Parameters to g13bec

---

nseries.....	1		
criteria.....	Nag_Exact	cfixed.....	Nag_FALSE
alpha.....	1.00e-02	beta.....	1.00e+01
delta.....	1.00e+03	gamma.....	1.00e-07
print_level.....	Nag_Soln		
outfile.....	stdout		

The number of iterations carried out is 15

The final values of the parameters and their standard deviations are

i	para[i]	sd
1	-0.094096	0.361543
2	-0.579152	0.295984
3	-0.611889	0.182241
4	9.932425	7.050207

The residual sum of squares = 9.436281e+03

The objective function = 9.762154e+03

The degrees of freedom = 25.00

RESIDUAL AUTOCORRELATION FUNCTION

---

LAG	K	1	2	3	4	5	6	7
R(K)		0.030	0.026	-0.039	0.043	-0.129	-0.062	-0.218
ST.ERROR		0.011	0.116	0.122	0.147	0.171	0.171	0.179

---

LAG	K	8	9	10
R(K)		-0.105	-0.024	-0.072
ST.ERROR		0.182	0.182	0.184

---