

# NAG Library Function Document

## nag\_opt\_one\_var\_deriv (e04bbc)

### 1 Purpose

nag\_opt\_one\_var\_deriv (e04bbc) searches for a minimum, in a given finite interval, of a continuous function of a single variable, using function and first derivative values. The method (based on cubic interpolation) is intended for functions which have a continuous first derivative (although it will usually work if the derivative has occasional discontinuities).

### 2 Specification

```
#include <nag.h>
#include <nage04.h>

void nag_opt_one_var_deriv (
    void (*funct)(double xc, double *fc, double *gc, Nag_Comm *comm),
    double e1, double e2, double *a, double *b, Integer max_fun, double *x,
    double *f, double *g, Nag_Comm *comm, NagError *fail)
```

### 3 Description

nag\_opt\_one\_var\_deriv (e04bbc) is applicable to problems of the form:

$$\text{Minimize } F(x) \quad \text{subject to } a \leq x \leq b$$

when the first derivative  $dF/dx$  can be calculated. nag\_opt\_one\_var\_deriv (e04bbc) normally computes a sequence of  $x$  values which tend in the limit to a minimum of  $F(x)$  subject to the given bounds. It also progressively reduces the interval  $[a, b]$  in which the minimum is known to lie. It uses the safeguarded quadratic-interpolation method described in Gill and Murray (1973).

You must supply a function **funct** to evaluate  $F(x)$  and its first derivative. The arguments **e1** and **e2** together specify the accuracy:

$$Tol(x) = \mathbf{e1} \times |x| + \mathbf{e2}$$

to which the position of the minimum is required. Note that **funct** is never called at any point which is closer than  $Tol(x)$  to a previous point.

If the original interval  $[a, b]$  contains more than one minimum, nag\_opt\_one\_var\_deriv (e04bbc) will normally find one of the minima.

### 4 References

Gill P E and Murray W (1973) Safeguarded steplength algorithms for optimization using descent methods *NPL Report NAC 37* National Physical Laboratory

### 5 Arguments

- 1: **funct** – function, supplied by the user *External Function*  
**funct** must calculate the values of  $F(x)$  and  $dF/dx$  at any point  $x$  in  $[a, b]$ .

The specification of **funct** is:

```
void funct (double xc, double *fc, double *gc, Nag_Comm *comm)
```

1:	<b>xc</b> – double	<i>Input</i>
	<i>On entry:</i> $x$ , the point at which the values of $F$ and $dF/dx$ are required.	
2:	<b>fc</b> – double *	<i>Output</i>
	<i>On exit:</i> the value of the function $F$ at the current point $x$ .	
3:	<b>gc</b> – double *	<i>Output</i>
	<i>On exit:</i> the value of the first derivative $dF/dx$ at the current point $x$ .	
4:	<b>comm</b> – Nag_Comm *	
	Pointer to structure of type Nag_Comm; the following members are relevant to <b>funct</b> .	
	<b>first</b> – Nag_Boolean	<i>Input</i>
	<i>On entry:</i> will be set to Nag_TRUE on the first call to <b>funct</b> and Nag_FALSE for all subsequent calls.	
	<b>nf</b> – Integer	<i>Input</i>
	<i>On entry:</i> the number of calls made to <b>funct</b> so far.	
	<b>user</b> – double *	
	<b>iuser</b> – Integer *	
	<b>p</b> – Pointer	
	The type Pointer will be <code>void *</code> with a C compiler that defines <code>void *</code> and <code>char *</code> otherwise. Before calling <code>nag_opt_one_var_deriv</code> (e04bbc) these pointers may be allocated memory and initialized with various quantities for use by <b>funct</b> when called from <code>nag_opt_one_var_deriv</code> (e04bbc).	

**Note:** **funct** should be tested separately before being used in conjunction with `nag_opt_one_var_deriv` (e04bbc).

- 2: **e1** – double *Input*
- On entry:* the relative accuracy to which the position of a minimum is required. (Note that since **e1** is a relative tolerance, the scaling of  $x$  is automatically taken into account.)
- It is recommended that **e1** should be no smaller than  $2\epsilon$ , and preferably not much less than  $\sqrt{\epsilon}$ , where  $\epsilon$  is the *machine precision*.
- If **e1** is set to a value less than  $\epsilon$ , its value is ignored and the default value of  $\sqrt{\epsilon}$  is used instead. In particular, you may set **e1** = 0.0 to ensure that the default value is used.
- 3: **e2** – double *Input*
- On entry:* the absolute accuracy to which the position of a minimum is required. It is recommended that **e2** should be no smaller than  $2\epsilon$ .
- If **e2** is set to a value less than  $\epsilon$ , its value is ignored and the default value of  $\sqrt{\epsilon}$  is used instead. In particular, you may set **e2** = 0.0 to ensure that the default value is used.
- 4: **a** – double \* *Input/Output*
- On entry:* the lower bound  $a$  of the interval containing a minimum.
- On exit:* an improved lower bound on the position of the minimum.
- 5: **b** – double \* *Input/Output*
- On entry:* the upper bound  $b$  of the interval containing a minimum.

*On exit:* an improved upper bound on the position of the minimum.

*Constraint:*  $\mathbf{b} > \mathbf{a} + \mathbf{e2}$ .

Note that the value  $\mathbf{e2} = \sqrt{\epsilon}$  applies here if  $\mathbf{e2} < \epsilon$  on entry to `nag_opt_one_var_deriv` (e04bbc).

6: **max\_fun** – Integer *Input*

*On entry:* the maximum number of calls to **funct** which you are prepared to allow.

The number of calls to **funct** actually made by `nag_opt_one_var_deriv` (e04bbc) may be determined by supplying a non-NULL argument **comm** (see below) and examining the structure member **comm**→**nf** on exit.

*Constraint:*  $\mathbf{max\_fun} \geq 2$ .

(Few problems will require more than 20 function calls.)

7: **x** – double \* *Output*

*On exit:* the estimated position of the minimum.

8: **f** – double \* *Output*

*On exit:* the value of  $F$  at the final point **x**.

9: **g** – double \* *Output*

*On exit:* the value of the first derivative  $dF/dx$  at the final point **x**.

10: **comm** – Nag\_Comm \* *Input/Output*

**Note:** **comm** is a NAG defined type (see Section 3.2.1.1 in the Essential Introduction).

*On entry/exit:* structure containing pointers for communication to user-supplied functions; see the above description of **funct** for details. The number of times the function **funct** was called is returned in the member **comm**→**nf**.

If you do not need to make use of this communication feature, the null pointer `NAGCOMM_NULL` may be used in the call to `nag_opt_one_var_deriv` (e04bbc); **comm** will then be declared internally for use in calls to user-supplied functions.

11: **fail** – NagError \* *Input/Output*

The NAG error argument (see Section 3.6 in the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_2\_REAL\_ARG\_GE

On entry,  $\mathbf{a} + \mathbf{e2} = \langle value \rangle$  while  $\mathbf{b} = \langle value \rangle$ . These arguments must satisfy  $\mathbf{a} + \mathbf{e2} < \mathbf{b}$ .

### NE\_INT\_ARG\_LT

On entry, **max\_fun** must not be less than 2:  $\mathbf{max\_fun} = \langle value \rangle$ .

### NW\_MAX\_FUN

The maximum number of function calls,  $\langle value \rangle$ , have been performed.

This may have happened simply because **max\_fun** was set too small for a particular problem, or may be due to a mistake in the user-supplied function, **funct**. If no mistake can be found in **funct**, restart `nag_opt_one_var_deriv` (e04bbc) (preferably with the values of **a** and **b** given on exit from the previous call to `nag_opt_one_var_deriv` (e04bbc)).

## 7 Accuracy

If  $F(x)$  is  $\delta$ -unimodal for some  $\delta < Tol(x)$ , where  $Tol(x) = \mathbf{e1} \times |x| + \mathbf{e2}$ , then, on exit,  $x$  approximates the minimum of  $F(x)$  in the original interval  $[a, b]$  with an error less than  $3 \times Tol(x)$ .

## 8 Parallelism and Performance

Not applicable.

## 9 Further Comments

Timing depends on the behaviour of  $F(x)$ , the accuracy demanded, and the length of the interval  $[a, b]$ . Unless  $F(x)$  and  $dF/dx$  can be evaluated very quickly, the run time will usually be dominated by the time spent in **funct**.

If  $F(x)$  has more than one minimum in the original interval  $[a, b]$ , `nag_opt_one_var_deriv` (e04bbc) will determine an approximation  $x$  (and improved bounds  $a$  and  $b$ ) for one of the minima.

If `nag_opt_one_var_deriv` (e04bbc) finds an  $x$  such that  $F(x - \delta_1) > F(x) < F(x + \delta_2)$  for some  $\delta_1, \delta_2 \geq Tol(x)$ , the interval  $[x - \delta_1, x + \delta_2]$  will be regarded as containing a minimum, even if  $F(x)$  is less than  $F(x - \delta_1)$  and  $F(x + \delta_2)$  only due to rounding errors in the user-supplied function. Therefore **funct** should be programmed to calculate  $F(x)$  as accurately as possible, so that `nag_opt_one_var_deriv` (e04bbc) will not be liable to find a spurious minimum. (For similar reasons,  $dF/dx$  should be evaluated as accurately as possible.)

## 10 Example

A sketch of the function

$$F(x) = \frac{\sin x}{x}$$

shows that it has a minimum somewhere in the range  $[3.5, 5.0]$ . The example program below shows how `nag_opt_one_var_deriv` (e04bbc) can be used to obtain a good approximation to the position of a minimum.

### 10.1 Program Text

```

/* nag_opt_one_var_deriv (e04bbc) Example Program.
 *
 * Copyright 2014 Numerical Algorithms Group.
 *
 * Mark 5, 1998.
 * Mark 7 revised, 2001.
 * Mark 8 revised, 2004.
 */

#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <math.h>
#include <nage04.h>

#ifdef __cplusplus
extern "C" {
#endif
static void NAG_CALL funct(double xc, double *fc, double *gc, Nag_Comm *comm);
#ifdef __cplusplus
}
#endif

static void NAG_CALL funct(double xc, double *fc, double *gc, Nag_Comm *comm)
{
    if (comm->user[0] == -1.0)

```

```

    {
        printf("(User-supplied callback funct, first invocation.)\n");
        comm->user[0] = 0.0;
    }
    *fc = sin(xc) / xc;
    *gc = (cos(xc) - *fc) / xc;
}
/* funct */

int main(void)
{
    static double ruser[1] = {-1.0};
    Integer      exit_status = 0, max_fun;
    NagError fail;
    Nag_Comm comm;
    double      a, b, e1, e2, f, g, x;

    INIT_FAIL(fail);

    printf("nag_opt_one_var_deriv (e04bbc) Example Program Results\n\n");

    /* For communication with user-supplied functions: */
    comm.user = ruser;

    /* e1 and e2 are set to zero so that nag_opt_one_var_no_deriv (e04abc) will
     * reset them to their default values
     */
    e1 = 0.0;
    e2 = 0.0;
    /* The minimum is known to lie in the range (3.5, 5.0) */
    a = 3.5;
    b = 5.0;
    /* Allow 30 calls of funct */
    max_fun = 30;
    /* nag_opt_one_var_deriv (e04bbc).
     * Minimizes a function of one variable, requires first
     * derivatives
     */
    nag_opt_one_var_deriv(funcnt, e1, e2, &a, &b, max_fun, &x, &f, &g, &comm,
                          &fail);
    if (fail.code != NE_NOERROR)
    {
        printf("Error from nag_opt_one_var_deriv (e04bbc).\n%s\n",
              fail.message);
        exit_status = 1;
        goto END;
    }

    printf("The minimum lies in the interval %7.5f to %7.5f.\n", a, b);
    printf("Its estimated position is %7.5f,\n", x);
    printf("where the function value is %13.4e\n", f);
    printf("and the gradient is %13.4e.\n", g);
    printf("%1"NAG_IFMT" function evaluations were required.\n", comm.nf);
END:
    return exit_status;
}

```

## 10.2 Program Data

None.

### 10.3 Program Results

nag\_opt\_one\_var\_deriv (e04bbc) Example Program Results

(User-supplied callback funct, first invocation.)  
The minimum lies in the interval 4.49341 to 4.49341.  
Its estimated position is 4.49341,  
where the function value is -2.1723e-01  
and the gradient is -3.7679e-16.  
6 function evaluations were required.

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