NAG Library Function Document

nag_1d_cheb_intg (e02ajc)

1 Purpose

nag_1d_cheb_intg (e02ajc) determines the coefficients in the Chebyshev series representation of the indefinite integral of a polynomial given in Chebyshev series form.

2 Specification

```
#include <nag.h>
#include <nage02.h>
```

3 Description

nag_1d_cheb_intg (e02ajc) forms the polynomial which is the indefinite integral of a given polynomial. Both the original polynomial and its integral are represented in Chebyshev series form. If supplied with the coefficients a_i , for $i = 0, 1, \ldots, n$, of a polynomial p(x) of degree n, where

$$p(x) = \frac{1}{2}a_0 + a_1T_1(\bar{x}) + \dots + a_nT_n(\bar{x}),$$

the function returns the coefficients a'_i , for i = 0, 1, ..., n + 1, of the polynomial q(x) of degree n + 1, where

$$q(x) = \frac{1}{2}a'_0 + a'_1T_1(\bar{x}) + \dots + a'_{n+1}T_{n+1}(\bar{x}),$$

and

$$q(x) = \int p(x)dx.$$

Here $T_j(\bar{x})$ denotes the Chebyshev polynomial of the first kind of degree j with argument \bar{x} . It is assumed that the normalized variable \bar{x} in the interval [-1,+1] was obtained from your original variable x in the interval $[x_{\min},x_{\max}]$ by the linear transformation

$$\bar{x} = \frac{2x - (x_{\text{max}} + x_{\text{min}})}{x_{\text{max}} - x_{\text{min}}}$$

and that you require the integral to be with respect to the variable x. If the integral with respect to \bar{x} is required, set $x_{\text{max}} = 1$ and $x_{\text{min}} = -1$.

Values of the integral can subsequently be computed, from the coefficients obtained, by using nag_1d_cheb_eval2 (e02akc).

The method employed is that of Chebyshev series (see Chapter 8 of Modern Computing Methods (1961)), modified for integrating with respect to x. Initially taking $a_{n+1} = a_{n+2} = 0$, the function forms successively

$$a_i' = \frac{a_{i-1} - a_{i+1}}{2i} \times \frac{x_{\max} - x_{\min}}{2}, \quad i = n+1, n, \dots, 1.$$

The constant coefficient a_0' is chosen so that q(x) is equal to a specified value, **qatm1**, at the lower end point of the interval on which it is defined, i.e., $\bar{x} = -1$, which corresponds to $x = x_{\min}$.

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4 References

Modern Computing Methods (1961) Chebyshev-series NPL Notes on Applied Science 16 (2nd Edition) HMSO

5 Arguments

1: \mathbf{n} - Integer Input

On entry: n, the degree of the given polynomial p(x).

Constraint: $\mathbf{n} \geq 0$.

2: **xmin** – double *Input*

3: xmax – double Input

On entry: the lower and upper end points respectively of the interval $[x_{\min}, x_{\max}]$. The Chebyshev series representation is in terms of the normalized variable \bar{x} , where

$$\bar{x} = \frac{2x - (x_{\text{max}} + x_{\text{min}})}{x_{\text{max}} - x_{\text{min}}}.$$

Constraint: xmax > xmin.

4: $\mathbf{a}[dim]$ – const double Input

Note: the dimension, dim, of the array **a** must be at least $(1 + (\mathbf{n} + 1 - 1) \times \mathbf{ia1})$.

On entry: the Chebyshev coefficients of the polynomial p(x). Specifically, element $i \times \mathbf{ia1}$ of a must contain the coefficient a_i , for $i = 0, 1, \dots, n$. Only these n + 1 elements will be accessed.

5: ia1 – Integer Input

On entry: the index increment of **a**. Most frequently the Chebyshev coefficients are stored in adjacent elements of **a**, and **ia1** must be set to 1. However, if for example, they are stored in $\mathbf{a}[0], \mathbf{a}[3], \mathbf{a}[6], \ldots$, then the value of **ia1** must be 3. See also Section 9.

Constraint: $ia1 \ge 1$.

6: qatm1 – double Input

On entry: the value that the integrated polynomial is required to have at the lower end point of its interval of definition, i.e., at $\bar{x} = -1$ which corresponds to $x = x_{\min}$. Thus, **qatm1** is a constant of integration and will normally be set to zero by you.

7: $\mathbf{aintc}[dim] - double$ Output

Note: the dimension, dim, of the array **aintc** must be at least $(1 + (\mathbf{n} + 1) \times \mathbf{iaint1})$.

On exit: the Chebyshev coefficients of the integral q(x). (The integration is with respect to the variable x, and the constant coefficient is chosen so that $q(x_{\min})$ equals **qatm1**). Specifically, element $i \times \mathbf{iaint1}$ of **aintc** contains the coefficient a'_i , for $i = 0, 1, \ldots, n+1$.

8: iaint1 – Integer Input

On entry: the index increment of aintc. Most frequently the Chebyshev coefficients are required in adjacent elements of aintc, and iaint1 must be set to 1. However, if, for example, they are to be stored in aintc[0], aintc[0], aintc[6],..., then the value of iaint1 must be 3. See also Section 9.

Constraint: $iaint1 \ge 1$.

9: fail – NagError * Input/Output

The NAG error argument (see Section 3.6 in the Essential Introduction).

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6 Error Indicators and Warnings

NE_ALLOC_FAIL

Dynamic memory allocation failed. See Section 3.2.1.2 in the Essential Introduction for further information.

NE BAD PARAM

On entry, argument \(\value \rangle \) had an illegal value.

NE INT

```
On entry, \mathbf{ia1} = \langle value \rangle.
Constraint: \mathbf{ia1} \ge 1.
On entry, \mathbf{iaint1} = \langle value \rangle.
Constraint: \mathbf{iaint1} \ge 1.
On entry, \mathbf{n} + 1 = \langle value \rangle.
Constraint: \mathbf{n} + 1 \ge 1.
On entry, \mathbf{n} = \langle value \rangle.
Constraint: \mathbf{n} \ge 0.
```

NE INTERNAL ERROR

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

An unexpected error has been triggered by this function. Please contact NAG. See Section 3.6.6 in the Essential Introduction for further information.

NE NO LICENCE

Your licence key may have expired or may not have been installed correctly. See Section 3.6.5 in the Essential Introduction for further information.

NE REAL 2

```
On entry, \mathbf{xmax} = \langle value \rangle and \mathbf{xmin} = \langle value \rangle. Constraint: \mathbf{xmax} > \mathbf{xmin}.
```

7 Accuracy

In general there is a gain in precision in numerical integration, in this case associated with the division by 2i in the formula quoted in Section 3.

8 Parallelism and Performance

Not applicable.

9 Further Comments

The time taken is approximately proportional to n+1.

The increments ia1, iaint1 are included as arguments to give a degree of flexibility which, for example, allows a polynomial in two variables to be integrated with respect to either variable without rearranging the coefficients.

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10 Example

Suppose a polynomial has been computed in Chebyshev series form to fit data over the interval [-0.5, 2.5]. The following program evaluates the integral of the polynomial from 0.0 to 2.0. (For the purpose of this example, **xmin**, **xmax** and the Chebyshev coefficients are simply supplied. Normally a program would read in or generate data and compute the fitted polynomial).

10.1 Program Text

```
/* nag_ld_cheb_intg (e02ajc) Example Program.
 * Copyright 2014 Numerical Algorithms Group.
* Mark 7, 2001.
#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nage02.h>
int main(void)
  /* Initialized data */
 const double xmin = -0.5;
 const double xmax = 2.5;
 const double a[7] =
 { 2.53213, 1.13032, 0.2715, 0.04434, 0.00547, 5.4e-4, 4e-5 };
  /* Scalars */
 double
              ra, rb, result, xa, xb, zero;
 Integer
               exit_status, n, one;
 NagError
               fail;
  /* Arrays */
               *aint = 0;
 double
 INIT_FAIL(fail);
 exit_status = 0;
 printf("nag_1d_cheb_intg (e02ajc) Example Program Results\n");
 n = 6;
 zero = 0.0;
 one = 1;
  /* Allocate memory */
 if (!(aint = NAG_ALLOC(n + 2, double)))
     printf("Allocation failure\n");
     exit_status = -1;
     goto END;
  /* nag_ld_cheb_intg (e02ajc).
   * Integral of fitted polynomial in Chebyshev series form
 nag_ld_cheb_intg(n, xmin, xmax, a, one, zero, aint, one, &fail);
  if (fail.code != NE_NOERROR)
    {
     printf("Error from nag_1d_cheb_intg (e02ajc).\n%s\n",
              fail.message);
      exit_status = 1;
      goto END;
 xa = 0.0;
 xb = 2.0;
  /* nag_1d_cheb_eval2 (e02akc).
```

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```
* Evaluation of fitted polynomial in one variable from
   * Chebyshev series form
 nag_1d_cheb_eval2(n+1, xmin, xmax, aint, one, xa, &ra, &fail);
 if (fail.code != NE_NOERROR)
   {
     printf("Error from nag_1d_cheb_eval2 (e02akc).\n%s\n",
              fail.message);
      exit_status = 1;
     goto END;
  /* nag_1d_cheb_eval2 (e02akc), see above. */
 nag_1d_cheb_eval2(n+1, xmin, xmax, aint, one, xb, &rb, &fail);
  if (fail.code != NE_NOERROR)
     printf("Error from nag_1d_cheb_eval2 (e02akc).\n%s\n",
              fail.message);
     exit_status = 1;
     goto END;
    }
 result = rb - ra;
 printf("\n");
 printf("Value of definite integral is %10.4f\n", result);
END:
 NAG_FREE(aint);
 return exit_status;
}
```

10.2 Program Data

None.

10.3 Program Results

```
nag_ld_cheb_intg (e02ajc) Example Program Results
Value of definite integral is 2.1515
```

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