

## NAG Library Function Document

### nag\_stable\_sort (m01ctc)

## 1 Purpose

nag\_stable\_sort (m01ctc) rearranges a vector of arbitrary type objects into ascending or descending order.

## 2 Specification

```
#include <nag.h>
#include <nagm01.h>
void nag_stable_sort (Pointer vec, size_t n, size_t size, ptrdiff_t stride,
    Integer (*compare)(const Nag_Pointer a, const Nag_Pointer b),
    Nag_SortOrder order, NagError *fail)
```

## 3 Description

nag\_stable\_sort (m01ctc) sorts a set of  $n$  data objects of arbitrary type, which are stored in the elements of an array at intervals of length **stride**. The function may be used to sort a column of a two-dimensional array. Either ascending or descending sort order may be specified.

A stable sort is one which preserves the order of distinct data items that compare equal. This function uses nag\_rank\_sort (m01dsc), nag\_make\_indices (m01zac) and nag\_reorder\_vector (m01esc) in order to carry out a stable sort with the same specification as nag\_quicksort (m01csc). nag\_stable\_sort (m01ctc) will be faster than nag\_quicksort (m01csc) if the comparison function **compare** is slow or the data items are large. Internally a large amount of workspace may be required compared with nag\_quicksort (m01csc).

## 4 References

Knuth D E (1973) *The Art of Computer Programming (Volume 3)* (2nd Edition) Addison–Wesley

## 5 Arguments

- |    |  |                     |
|----|--|---------------------|
| 1: | <b>vec[n]</b> – Pointer  | <i>Input/Output</i> |
|    | <i>On entry</i> : the array of objects to be sorted.                           |                     |
|    | <i>On exit</i> : the objects rearranged into sorted order.                     |                     |
| 2: | <b>n</b> – size_t  | <i>Input</i>        |
|    | <i>On entry</i> : the number $n$ of objects to be sorted.                      |                     |
|    | <i>Constraint</i> : <b>n</b> $\geq 0$ .  |                     |
| 3: | <b>size</b> – size_t   | <i>Input</i>        |
|    | <i>On entry</i> : the size of each object to be sorted.                        |                     |
|    | <i>Constraint</i> : <b>size</b> $\geq 1$ .                                     |                     |
| 4: | <b>stride</b> – ptrdiff_t  | <i>Input</i>        |
|    | <i>On entry</i> : the increment between data items in <b>vec</b> to be sorted. |                     |

**Note:** if **stride** is positive, **vec** should point at the first data object; otherwise **vec** should point at the last data object.

*Constraint:*  $|\text{stride}| \geq \text{size}$ .

5: **compare** – function, supplied by the user *External Function*

`nag_stable_sort (m01ctc)` compares two data objects. If its arguments are pointers to a structure, this function must allow for the offset of the data field in the structure (if it is not the first).

The function must return:

- 1if the first data field is less than the second,
- 0if the first data field is equal to the second,
- 1if the first data field is greater than the second.

The specification of **compare** is:

```
Integer compare (const Nag_Pointer a, const Nag_Pointer b)
```

1:   **a** – const Nag\_Pointer *Input*

*On entry:* the first data field.

2:   **b** – const Nag\_Pointer *Input*

*On entry:* the second data field.

6: **order** – Nag\_SortOrder *Input*

*On entry:* specifies whether the array is to be sorted into ascending or descending order.

*Constraint:* **order** = Nag\_Ascending or Nag\_Descending.

7: **fail** – NagError \* *Input/Output*

The NAG error argument (see Section 3.6 in the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_2\_INT\_ARG\_LT

On entry,  $|\text{stride}| = \langle \text{value} \rangle$  while  $\text{size} = \langle \text{value} \rangle$ . These arguments must satisfy  $|\text{stride}| \geq \text{size}$ .

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

### NE\_BAD\_PARAM

On entry, argument **order** had an illegal value.

### NE\_INT\_ARG\_GT

On entry, **n** =  $\langle \text{value} \rangle$ .

*Constraint:*  $\mathbf{n} \leq \langle \text{value} \rangle$ .

On entry, **size** =  $\langle \text{value} \rangle$ .

*Constraint:*  $\mathbf{size} \leq \langle \text{value} \rangle$ .

On entry, **stride** =  $\langle \text{value} \rangle$ .

*Constraint:*  $|\text{stride}| \leq \langle \text{value} \rangle$ .

These arguments are limited to an implementation-dependent size which is printed in the error message.

**NE\_INT\_ARG\_LT**

On entry, **n** =  $\langle value \rangle$ .

Constraint: **n**  $\geq 0$ .

On entry, **size** =  $\langle value \rangle$ .

Constraint: **size**  $\geq 1$ .

The absolute value of **stride** must not be less than **size**.

**7 Accuracy**

Not applicable.

**8 Parallelism and Performance**

Not applicable.

**9 Further Comments**

The time taken by nag\_stable\_sort (m01ctc) is approximately proportional to  $n \log(n)$ .

**10 Example**

The example program reads a three column matrix of real numbers and sorts the first column into ascending order.

**10.1 Program Text**

```
/* nag_stable_sort (m01ctc) Example Program.
*
* Copyright 1990 Numerical Algorithms Group.
*
* Mark 2 revised, 1992.
* Mark 7 revised, 2001.
* Mark 8 revised, 2004.
*/
#include <nag.h>
#include <stdio.h>
#include <nag_stdlib.h>
#include <nag_stdef.h>
#include <nagm01.h>

#ifndef __cplusplus
extern "C" {
#endif
static Integer NAG_CALL compare(const Nag_Pointer a, const Nag_Pointer b);
#ifndef __cplusplus
}
#endif

#define VEC(I, J) vec[(I) *tdvec + J]
int main(void)
{
    Integer exit_status = 0, i, j, k, m, n, tdvec;
    NagError fail;
    double *vec = 0;

    INIT_FAIL(fail);

    /* Skip heading in data file */
    scanf("%*[^\n]");
    printf("nag_stable_sort (m01ctc) Example Program Results\n");
}
```

```

scanf("%ld%ld%ld", &m, &n, &k);
if (m >= 0 && n >= 0 && k >= 0 && k <= n)
{
    if (!(vec = NAG_ALLOC(m*n, double)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
    tdvec = n;
}
else
{
    printf("Invalid m or n or k.\n");
    exit_status = 1;
    return exit_status;
}
for (i = 0; i < m; ++i)
    for (j = 0; j < n; ++j)
        scanf("%lf", &VEC(i, j));
/* nag_stable_sort (m01ctc).
 * Stable sort of set of values of arbitrary data type
 */
nag_stable_sort((Pointer) &VEC(0, k-1), (size_t) m, sizeof(double),
                 (ptrdiff_t)(n*sizeof(double)), compare, Nag_Ascending,
                 &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_stable_sort (m01ctc).\n%s\n",
           fail.message);
    exit_status = 1;
    goto END;
}

printf("\nMatrix with column %ld sorted\n", k);
for (i = 0; i < m; ++i)
{
    for (j = 0; j < n; ++j)
        printf(" %7.1f ", VEC(i, j));
    printf("\n");
}
END:
NAG_FREE(vec);
return exit_status;
}

static Integer NAG_CALL compare(const Nag_Pointer a, const Nag_Pointer b)
{
    double x = *((const double *) a);
    double y = *((const double *) b);
    return(x < y?-1:(x == y?0:1));
}

```

## 10.2 Program Data

```

nag_stable_sort (m01ctc) Example Program Data
12 3 1
6.0 5.0 4.0
5.0 2.0 1.0
2.0 4.0 9.0
4.0 9.0 6.0
4.0 9.0 5.0
4.0 1.0 2.0
3.0 4.0 1.0
2.0 4.0 6.0
1.0 6.0 4.0
9.0 3.0 2.0
6.0 2.0 5.0
4.0 9.0 6.0

```

### 10.3 Program Results

```
nag_stable_sort (m01ctc) Example Program Results
```

```
Matrix with column 1 sorted
```

1.0	5.0	4.0
2.0	2.0	1.0
2.0	4.0	9.0
3.0	9.0	6.0
4.0	9.0	5.0
4.0	1.0	2.0
4.0	4.0	1.0
4.0	4.0	6.0
5.0	6.0	4.0
6.0	3.0	2.0
6.0	2.0	5.0
9.0	9.0	6.0