

# NAG Library Function Document

## nag\_mv\_factor (g03cac)

### 1 Purpose

nag\_mv\_factor (g03cac) computes the maximum likelihood estimates of the arguments of a factor analysis model. Either the data matrix or a correlation/covariance matrix may be input. Factor loadings, communalities and residual correlations are returned.

### 2 Specification

```
#include <nag.h>
#include <nagg03.h>

void nag_mv_factor (Nag_FacMat matrix, Integer n, Integer m,
  const double x[], Integer tdx, Integer nvar, const Integer isx[],
  Integer nfac, const double wt[], double e[], double stat[],
  double com[], double psi[], double res[], double fl[], Integer tdf1,
  Nag_E04_Opt *options, double eps, NagError *fail)
```

### 3 Description

Let  $p$  variables,  $x_1, x_2, \dots, x_p$ , with variance-covariance matrix  $\Sigma$  be observed. The aim of factor analysis is to account for the covariances in these  $p$  variables in terms of a smaller number,  $k$ , of hypothetical variables, or factors,  $f_1, f_2, \dots, f_k$ . These are assumed to be independent and to have unit variance. The relationship between the observed variables and the factors is given by the model:

$$x_i = \sum_{j=1}^k \lambda_{ij} f_j + e_i$$

$\lambda_{ij}$ , for  $i = 1, 2, \dots, p$  and  $j = 1, 2, \dots, k$ , are the factor loadings and  $e_i$ , for  $i = 1, 2, \dots, p$ , are independent random variables with variances  $\psi_i$ , for  $i = 1, 2, \dots, p$ . The  $\psi_i$  represent the unique component of the variation of each observed variable. The proportion of variation for each variable accounted for by the factors is known as the communality. For this function it is assumed that both the  $k$  factors and the  $e_i$ 's follow independent Normal distributions.

The model for the variance-covariance matrix,  $\Sigma$ , can be written as:

$$\Sigma = \Lambda \Lambda^T + \Psi \quad (1)$$

where  $\Lambda$  is the matrix of the factor loadings,  $\lambda_{ij}$ , and  $\Psi$  is a diagonal matrix of unique variances,  $\psi_i$ , for  $i = 1, 2, \dots, p$ .

The estimation of the arguments of the model,  $\Lambda$  and  $\Psi$ , by maximum likelihood is described by Lawley and Maxwell (1971). The log likelihood is:

$$-\frac{1}{2}(n-1)\log(|\Sigma|) - \frac{1}{2}(n-1)\text{trace}(S\Sigma^{-1}) + \text{constant},$$

where  $n$  is the number of observations,  $S$  is the sample variance-covariance matrix or, if weights are used,  $S$  is the weighted sample variance-covariance matrix and  $n$  is the effective number of observations, that is, the sum of the weights. The constant is independent of the arguments of the model. A two stage maximization is employed. It makes use of the function  $F(\Psi)$ , which is, up to a constant,  $-2/(n-1)$  times the log likelihood maximized over  $\Lambda$ . This is then minimized with respect to  $\Psi$  to give the estimates,  $\hat{\Psi}$ , of  $\Psi$ . The function  $F(\Psi)$  can be written as:

$$F(\Psi) = \sum_{j=k+1}^p (\theta_j - \log \theta_j) - (p - k),$$

where values  $\theta_j$ , for  $j = 1, 2, \dots, p$  are the eigenvalues of the matrix:

$$S^* = \Psi^{-1/2} S \Psi^{-1/2}.$$

The estimates  $\hat{\Lambda}$ , of  $\Lambda$ , are then given by scaling the eigenvectors of  $S^*$ , which are denoted by  $V$ :

$$\hat{\Lambda} = \Psi^{1/2} V(\Theta - I)^{1/2}.$$

where  $\Theta$  is the diagonal matrix with elements  $\theta_i$ , and  $I$  is the identity matrix.

The minimization of  $F(\Psi)$  is performed using `nag_opt_bounds_2nd_deriv (e04lbc)` which uses a modified Newton algorithm. The computation of the Hessian matrix is described by Clark (1970). However, instead of using the eigenvalue decomposition of the matrix  $S^*$  as described above, the singular value decomposition of the matrix  $R\Psi^{-1/2}$  is used, where  $R$  is obtained either from the  $QR$  decomposition of the (scaled) mean-centred data matrix or from the Cholesky decomposition of the correlation/covariance matrix. The function `nag_opt_bounds_2nd_deriv (e04lbc)` ensures that the values of  $\psi_i$  are greater than a given small positive quantity,  $\delta$ , so that the communality is always less than one. This avoids the so called Heywood cases.

In addition to the values of  $\Lambda$ ,  $\Psi$  and the communalities, `nag_mv_factor (g03cac)` returns the residual correlations, i.e., the off-diagonal elements of  $C - (\Lambda\Lambda^T + \Psi)$  where  $C$  is the sample correlation matrix. `nag_mv_factor (g03cac)` also returns the test statistic:

$$\chi^2 = [n - 1 - (2p + 5)/6 - 2k/3]F(\hat{\Psi})$$

which can be used to test the goodness-of-fit of the model (1), see Lawley and Maxwell (1971) and Morrison (1967).

## 4 References

Clark M R B (1970) A rapidly convergent method for maximum likelihood factor analysis *British J. Math. Statist. Psych.*

Hammarling S (1985) The singular value decomposition in multivariate statistics *SIGNUM Newsl.* **20(3)** 2–25

Lawley D N and Maxwell A E (1971) *Factor Analysis as a Statistical Method* (2nd Edition) Butterworths  
Morrison D F (1967) *Multivariate Statistical Methods* McGraw–Hill

## 5 Arguments

1: **matrix** – Nag\_FacMat *Input*

*On entry:* selects the type of matrix on which factor analysis is to be performed.

**matrix** = Nag\_DataCorr (Data input)

The data matrix will be input in **x** and factor analysis will be computed for the correlation matrix.

**matrix** = Nag\_DataCovar

The data matrix will be input in **x** and factor analysis will be computed for the covariance matrix, i.e., the results are scaled as described in Section 9.

**matrix** = Nag\_MatCorr\_Covar

The correlation/variance-covariance matrix will be input in **x** and factor analysis computed for this matrix.

*Constraint:* **matrix** = Nag\_DataCorr, Nag\_DataCovar or Nag\_MatCorr\_Covar.

2: **n** – Integer *Input*

*On entry:* if **matrix** = Nag\_DataCorr or Nag\_DataCovar the number of observations in the data array **x**.

If **matrix** = Nag\_MatCorr\_Covar the (effective) number of observations used in computing the (possibly weighted) correlation/variance-covariance matrix input in **x**.

*Constraint:* **n** > **nvar**.

- 3: **m** – Integer *Input*  
*On entry:* the number of variables in the data/correlation/variance-covariance matrix.  
*Constraint:* **m** ≥ **nvar**.
- 4: **x**[*dim1* × **tdx**] – const double *Input*  
*On entry:* the input matrix.  
**matrix** = Nag\_DataCorr or Nag\_DataCovar  
**x** must contain the data matrix, i.e., **x**[(*i* – 1) × **tdx** + *j* – 1] must contain the *i*th observation for the *j*th variable, for *i* = 1, 2, ..., *n* and *j* = 1, 2, ..., **m**.  
**matrix** = Nag\_MatCorr\_Covar  
**x** must contain the correlation or variance-covariance matrix. Only the upper triangular part is required.
- 5: **tdx** – Integer *Input*  
*On entry:* the stride separating matrix column elements in the array **x**.  
*Constraint:* **tdx** ≥ **m**.
- 6: **nvar** – Integer *Input*  
*On entry:* the number of variables in the factor analysis, *p*.  
*Constraint:* **nvar** ≥ 2.
- 7: **isx**[**m**] – const Integer *Input*  
*On entry:* **isx**[*j* – 1] indicates whether or not the *j*th variable is to be included in the factor analysis.  
If **isx**[*j* – 1] ≥ 1, then the variable represented by the *j*th column of **x** is included in the analysis; otherwise it is excluded, for *j* = 1, 2, ..., **m**.  
*Constraint:* **isx**[*j* – 1] > 0 for **nvar** values of *j*.
- 8: **nfac** – Integer *Input*  
*On entry:* the number of factors, *k*.  
*Constraint:* 1 ≤ **nfac** ≤ **nvar**.
- 9: **wt**[**n**] – const double *Input*  
*On entry:* if **matrix** = Nag\_DataCorr or Nag\_DataCovar then the elements of **wt** must contain the weights to be used in the factor analysis. The effective number of observations is the sum of the weights. If **wt**[*i* – 1] = 0.0 then the *i*th observation is not included in the analysis.  
If **matrix** = Nag\_MatCorr\_Covar or **wt** is NULL then **wt** is not referenced and the effective number of observations is *n*.  
*Constraint:* if **wt** is referenced, then **wt**[*i* – 1] ≥ 0 for *i* = 1, 2, ..., *n*, and the sum of the weights > **nvar**.
- 10: **e**[**nvar**] – double *Output*  
*On exit:* the eigenvalues  $\theta_i$ , for *i* = 1, 2, ..., *p*.

- 11: **stat[4]** – double *Output*  
*On exit:* the test statistics.  
**stat[0]** contains the value  $F(\hat{\Psi})$ .  
**stat[1]** contains the test statistic,  $\chi^2$ .  
**stat[2]** contains the degrees of freedom associated with the test statistic.  
**stat[3]** contains the significance level.
- 12: **com[nvar]** – double *Output*  
*On exit:* the communalities.
- 13: **psi[nvar]** – double *Output*  
*On exit:* the estimates of  $\psi_i$ , for  $i = 1, 2, \dots, p$ .
- 14: **res[nvar × (nvar – 1)/2]** – double *Output*  
*On exit:* the residual correlations. The residual correlation for the  $i$ th and  $j$ th variables is stored in **res**[( $j - 1$ )( $j - 2$ )/2 +  $i - 1$ ],  $i < j$ .
- 15: **fl[nvar × tdf]** – double *Output*  
*On exit:* the factor loadings. **fl**[( $i - 1$ ) × **tdf** +  $j - 1$ ] contains  $\lambda_{ij}$ , for  $i = 1, 2, \dots, p$  and  $j = 1, 2, \dots, k$ .
- 16: **tdf** – Integer *Input*  
*On entry:* the stride separating matrix column elements in the array **fl**.  
*Constraint:* **tdf** ≥ **nfac**.
- 17: **options** – Nag\_E04\_Opt \* *Input/Output*  
*On entry/exit:* a pointer to a structure of type Nag\_E04\_Opt whose members are optional arguments for nag\_opt\_bounds\_2nd\_deriv (e04lbc). These structure members offer the means of adjusting some of the argument values of the algorithm.  
 If the optional arguments are not required the NAG defined null pointer, E04\_DEFAULT, can be used in the function call. See the document for nag\_opt\_bounds\_2nd\_deriv (e04lbc) for further details.
- 18: **eps** – double *Input*  
*On entry:* a lower bound for the value of  $\Psi_i$ .  
*Constraint:* *machine precision* ≤ **eps** < 1.0.
- 19: **fail** – NagError \* *Input/Output*  
 The NAG error argument (see Section 3.6 in the Essential Introduction).

## 6 Error Indicators and Warnings

### NE\_2\_INT\_ARG\_GT

On entry, **nfac** = *<value>* while **nvar** = *<value>*. These arguments must satisfy **nfac** ≤ **nvar**.

### NE\_2\_INT\_ARG\_LE

On entry, **n** = *<value>* while **nvar** = *<value>*. These arguments must satisfy **n** > **nvar**.

**NE\_2\_INT\_ARG\_LT**

On entry, **m** =  $\langle value \rangle$  while **nvar** =  $\langle value \rangle$ . These arguments must satisfy  $\mathbf{m} \geq \mathbf{nvar}$ .

On entry, **tdfl** =  $\langle value \rangle$  while **nfac** =  $\langle value \rangle$ . These arguments must satisfy  $\mathbf{tdfl} \geq \mathbf{nfac}$ .

On entry, **tdx** =  $\langle value \rangle$  while **m** =  $\langle value \rangle$ . These arguments must satisfy  $\mathbf{tdx} \geq \mathbf{m}$ .

**NE\_2\_REAL\_ARG\_LT**

On entry, **step\_max** =  $\langle value \rangle$  while **optim\_tol** =  $\langle value \rangle$ . These arguments must satisfy  $\mathbf{step\_max} \geq \mathbf{optim\_tol}$ .

**NE\_ALLOC\_FAIL**

Dynamic memory allocation failed.

**NE\_BAD\_PARAM**

On entry, argument **matrix** had an illegal value.

On entry, argument **print\_level** had an illegal value.

**NE\_INT\_ARG\_LT**

On entry, **nfac** =  $\langle value \rangle$ .

Constraint:  $\mathbf{nfac} \geq 1$ .

On entry, **nvar** =  $\langle value \rangle$ .

Constraint:  $\mathbf{nvar} \geq 2$ .

**NE\_INTERNAL\_ERROR**

Additional error messages are output if the optimization fails to converge or if the options are set incorrectly. Details of these can be found in the nag\_opt\_bounds\_2nd\_deriv (e04lbc) document.

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please contact NAG for assistance.

**NE\_INVALID\_INT\_RANGE\_1**

Value  $\langle value \rangle$  given to **max\_iter** is not valid. Correct range is  $\mathbf{max\_iter} \geq 0$ .

**NE\_INVALID\_REAL\_RANGE\_EF**

Value  $\langle value \rangle$  given to **eps** is not valid. Correct range is  $\mathbf{machine\ precision} \leq \mathbf{optim\_tol} < 1.0$ .

**NE\_INVALID\_REAL\_RANGE\_FF**

Value  $\langle value \rangle$  given to **linesearch\_tol** is not valid. Correct range is  $0.0 \leq \mathbf{linesearch\_tol} < 1.0$ .

**NE\_MAT\_RANK**

On entry, **matrix** = Nag\_DataCorr or **matrix** = Nag\_DataCovar and the data matrix is not of full column rank, or **matrix** = Nag\_MatCorr\_Covar and the input correlation/variance-covariance matrix is not positive definite. This exit may also be caused by two of the eigenvalues of  $S^*$  being equal; this is rare (see Lawley and Maxwell (1971)) and may be due to the data/correlation matrix being almost singular.

**NE\_NEG\_WEIGHT\_ELEMENT**

On entry,  $\mathbf{wt}[\langle value \rangle] = \langle value \rangle$ .

Constraint: when referenced, all elements of **wt** must be non-negative.

**NE\_NOT\_APPEND\_FILE**

Cannot open file  $\langle string \rangle$  for appending.

**NE\_NOT\_CLOSE\_FILE**

Cannot close file  $\langle string \rangle$ .

**NE\_OBSERV\_LT\_VAR**

With weighted data, the effective number of observations given by the sum of weights =  $\langle value \rangle$ , while the number of variables included in the analysis, **nvar** =  $\langle value \rangle$ .  
Constraint: effective number of observations > **nvar** + 1.

**NE\_OPT\_NOT\_INIT**

Options structure not initialized.

**NE\_SVD\_NOT\_CONV**

A singular value decomposition has failed to converge. This is a very unlikely error exit.

**NE\_VAR\_INCL\_INDICATED**

The number of variables, **nvar** in the analysis =  $\langle value \rangle$ , while number of variables included in the analysis via array **isx** =  $\langle value \rangle$ .  
Constraint: these two numbers must be the same.

**NW\_COND\_MIN**

The conditions for a minimum have not all been satisfied but a lower point could not be found. Note that in this case all the results are computed. See nag\_opt\_bounds\_2nd\_deriv (e04lbc) for further details.

**NW\_TOO\_MANY\_ITER**

The maximum number of iterations,  $\langle value \rangle$ , have been performed.

**7 Accuracy**

The accuracy achieved is discussed in nag\_opt\_bounds\_2nd\_deriv (e04lbc).

**8 Parallelism and Performance**

Not applicable.

**9 Further Comments**

The factor loadings may be orthogonally rotated by using nag\_mv\_orthomax (g03bac) and factor score coefficients can be computed using nag\_mv\_fac\_score (g03ccc). The maximum likelihood estimators are invariant to a change in scale. This means that the results obtained will be the same (up to a scaling factor) if either the correlation matrix or the variance-covariance matrix is used. As the correlation matrix ensures that all values of  $\psi_i$  are between 0 and 1 it will lead to a more efficient optimization. In the situation when the data matrix is input the results are always computed for the correlation matrix and then scaled if the results for the covariance matrix are required. When you input the covariance/correlation matrix the input matrix itself is used and so you are advised to input the correlation matrix rather than the covariance matrix.

**10 Example**

The example is taken from Lawley and Maxwell (1971). The correlation matrix for nine variables is input and the arguments of a factor analysis model with three factors are estimated and printed.

## 10.1 Program Text

```

/* nag_mv_factor (g03cac) Example Program.
 *
 * Copyright 1998 Numerical Algorithms Group.
 *
 * Mark 5, 1998.
 * Mark 8 revised, 2004.
 *
 */

#include <nag.h>
#include <stdio.h>
#include <string.h>
#include <nag_stdlib.h>
#include <nage04.h>
#include <nagg03.h>

#define FL(I, J) fl[(I) *tdfl + J]
#define X(I, J) x[(I) *tdx + J]
int main(void)
{
    Integer      exit_status = 0, i, *isx = 0, j, l, m, n, nfac, nvar, tdf1, tdx;
    double       *com = 0, *e = 0, eps, *fl = 0, *psi = 0, *res = 0, *stat = 0;
    double       *wt = 0, *wtptr = 0, *x = 0;
    char         nag_enum_arg[40];
    Nag_Boolean  weight;
    Nag_E04_Opt  options;
    Nag_FacMat   matrix;
    NagError     fail;

    INIT_FAIL(fail);

    printf("nag_mv_factor (g03cac) Example Program Results\n\n");

    /* Skip headings in data file */
    scanf("%*[^\\n]");
    scanf("%39s", nag_enum_arg);
    /* nag_enum_name_to_value (x04nac).
     * Converts NAG enum member name to value
     */
    matrix = (Nag_FacMat) nag_enum_name_to_value(nag_enum_arg);
    scanf("%39s", nag_enum_arg);
    weight = (Nag_Boolean) nag_enum_name_to_value(nag_enum_arg);
    scanf("%ld", &n);
    scanf("%ld", &m);
    scanf("%ld", &nvar);
    scanf("%ld", &nfac);

    if (nvar >= 2 && m >= nvar && n > nvar)
    {
        if (!(com = NAG_ALLOC(nvar, double)) ||
            !(e = NAG_ALLOC(nvar, double)) ||
            !(fl = NAG_ALLOC(nvar*nfac, double)) ||
            !(psi = NAG_ALLOC(nvar, double)) ||
            !(res = NAG_ALLOC(nvar*(nvar-1)/2, double)) ||
            !(stat = NAG_ALLOC(4, double)) ||
            !(wt = NAG_ALLOC(n, double)) ||
            !(x = NAG_ALLOC((matrix == Nag_MatCorr_Covar?m:n)*m, double)) ||
            !(isx = NAG_ALLOC(m, Integer)))
        {
            printf("Allocation failure\n");
            exit_status = -1;
            goto END;
        }
        tdf1 = nfac;
        tdx = m;
    }
    else
    {
        printf("Invalid nvar or m or n.\n");
    }
}

```

```

        exit_status = 1;
        return exit_status;
    }
    if (matrix == Nag_MatCorr_Covar)
    {
        for (i = 0; i < m; ++i)
        {
            for (j = 0; j < m; ++j)
                scanf("%lf", &X(i, j));
        }
    }
    else
    {
        if (weight)
        {
            for (i = 0; i < n; ++i)
            {
                for (j = 0; j < m; ++j)
                    scanf("%lf", &X(i, j));
                scanf("%lf", &wt[i]);
            }
            wtptr = wt;
        }
        else
        {
            for (i = 0; i < n; ++i)
            {
                for (j = 0; j < m; ++j)
                    scanf("%lf", &X(i, j));
            }
        }
    }
    for (j = 0; j < m; ++j)
        scanf("%ld", &isx[j]);

    /* nag_opt_init (e04xxc).
     * Initialization function for option setting
     */
    nag_opt_init(&options);
    options.max_iter = 500;
    options.optim_tol = 1e-2;
    eps = 1e-5;
    /* nag_mv_factor (g03cac).
     * Maximum likelihood estimates of parameters
     */
    fflush(stdout);
    nag_mv_factor(matrix, n, m, x, tdx, nvar, isx, nfac, wtptr, e,
                 stat, com, psi, res, fl, tdf, &options, eps, &fail);
    if (fail.code != NE_NOERROR)
    {
        printf("Error from nag_mv_factor (g03cac).\n%s\n", fail.message);
        exit_status = 1;
        goto END;
    }
    printf("\nEigenvalues\n\n");
    for (j = 0; j < nvar; ++j)
    {
        printf(" %13.4e%s", e[j], (j+1)%6 == 0?"\n":""");
    }
    printf("\n\n%s%6.3f\n", "    Test Statistic = ", stat[1]);
    printf("%s%6.3f\n", "    df = ", stat[2]);
    printf("%s%6.3f\n\n", "Significance level = ", stat[3]);
    printf("Residuals\n\n");
    l = 1;
    for (i = 1; i <= nvar-1; ++i)
    {
        for (j = 1; j <= l+i-1; ++j)
            printf(" %8.3f", res[j-1]);
        printf("\n");
        l += i;
    }

```



```

printf("\nLoadings, Communalities and PSI\n\n");
for (i = 0; i < nvar; ++i)
{
    for (j = 0; j < nfac; ++j)
        printf(" %8.3f", FL(i, j));
    printf("%8.3f%8.3f\n", com[i], psi[i]);
}

END:
NAG_FREE(com);
NAG_FREE(e);
NAG_FREE(fl);
NAG_FREE(psi);
NAG_FREE(res);
NAG_FREE(stat);
NAG_FREE(wt);
NAG_FREE(x);
NAG_FREE(isx);

return exit_status;
}

```

## 10.2 Program Data

```

nag_mv_factor (g03cac) Example Program Data
Nag_MatCorr_Covar Nag_FALSE 211 9 9 3
1.000 0.523 0.395 0.471 0.346 0.426 0.576 0.434 0.639
0.523 1.000 0.479 0.506 0.418 0.462 0.547 0.283 0.645
0.395 0.479 1.000 0.355 0.270 0.254 0.452 0.219 0.504
0.471 0.506 0.355 1.000 0.691 0.791 0.443 0.285 0.505
0.346 0.418 0.270 0.691 1.000 0.679 0.383 0.149 0.409
0.426 0.462 0.254 0.791 0.679 1.000 0.372 0.314 0.472
0.576 0.547 0.452 0.443 0.383 0.372 1.000 0.385 0.680
0.434 0.283 0.219 0.285 0.149 0.314 0.385 1.000 0.470
0.639 0.645 0.504 0.505 0.409 0.472 0.680 0.470 1.000
1 1 1 1 1 1 1 1 1

```

## 10.3 Program Results

nag\_mv\_factor (g03cac) Example Program Results

Parameters to e04lbc

```

-----
Number of variables..... 9

optim_tol..... 1.00e-02    linesearch_tol..... 9.00e-01
step_max..... 2.70e+01    max_iter..... 500
print_level..... Nag_Soln_Iter    machine precision..... 1.11e-16
deriv_check..... Nag_FALSE
outfile..... stdout

```

Memory allocation:

```

state..... User
hesl..... User    hesd..... User

```

```

Iterations performed = 0,    function evaluations = 1
Criterion = 8.635756e-02

```

Variable	Standardized Communalities
1	0.5755
2	0.5863
3	0.4344
4	0.7496
5	0.6203
6	0.7329
7	0.6061
8	0.4053

9 0.7104

Iterations performed = 1, function evaluations = 3  
 Criterion = 3.603203e-02

Variable	Standardized Communalities
1	0.5517
2	0.5800
3	0.3936
4	0.7926
5	0.6140
6	0.8254
7	0.6052
8	0.5076
9	0.7569

Iterations performed = 2, function evaluations = 4  
 Criterion = 3.502097e-02

Variable	Standardized Communalities
1	0.5496
2	0.5731
3	0.3838
4	0.7875
5	0.6200
6	0.8238
7	0.6006
8	0.5349
9	0.7697

Iterations performed = 3, function evaluations = 5  
 Criterion = 3.501729e-02

Variable	Standardized Communalities
1	0.5495
2	0.5729
3	0.3835
4	0.7877
5	0.6195
6	0.8231
7	0.6005
8	0.5384
9	0.7691

Eigenvalues

1.5968e+01 4.3577e+00 1.8474e+00 1.1560e+00 1.1190e+00 1.0271e+00  
 9.2574e-01 8.9508e-01 8.7710e-01

Test Statistic = 7.149  
 df = 12.000  
 Significance level = 0.848

Residuals

0.000  
 -0.013 0.022  
 0.011 -0.005 0.023  
 -0.010 -0.019 -0.016 0.003  
 -0.005 0.011 -0.012 -0.001 -0.001  
 0.015 -0.022 -0.011 0.002 0.029 -0.012  
 -0.001 -0.011 0.013 0.005 -0.006 -0.001 0.003  
 -0.006 0.010 -0.005 -0.011 0.002 0.007 0.003 -0.001

Loadings, Communalities and PSI

0.664 -0.321 0.074 0.550 0.450  
 0.689 -0.247 -0.193 0.573 0.427

0.493	-0.302	-0.222	0.383	0.617
0.837	0.292	-0.035	0.788	0.212
0.705	0.315	-0.153	0.619	0.381
0.819	0.377	0.105	0.823	0.177
0.661	-0.396	-0.078	0.600	0.400
0.458	-0.296	0.491	0.538	0.462
0.766	-0.427	-0.012	0.769	0.231

---