

NAG Library Function Document

nag_regsn_mult_linear_tran_model (g02dkc)

1 Purpose

nag_regsn_mult_linear_tran_model (g02dkc) calculates the estimates of the arguments of a general linear regression model for given constraints from the singular value decomposition results.

2 Specification

```
#include <nag.h>
#include <nagg02.h>
void nag_regsn_mult_linear_tran_model (Integer ip, Integer iconst,
    const double p[], const double c[], Integer tdc, double b[], double rss,
    double df, double se[], double cov[], NagError *fail)
```

3 Description

nag_regsn_mult_linear_tran_model (g02dkc) computes the estimates given a set of linear constraints for a general linear regression model which is not of full rank. It is intended for use after a call to nag_regsn_mult_linear (g02dac) or nag_regsn_mult_linear_upd_model (g02ddc).

In the case of a model not of full rank the functions use a singular value decomposition (SVD) to find the parameter estimates, $\hat{\beta}_{svd}$, and their variance-covariance matrix. Details of the SVD are made available, in the form of the matrix P^* :

$$P^* = \begin{pmatrix} D^{-1}P_1^T \\ P_0^T \end{pmatrix}$$

as described by nag_regsn_mult_linear (g02dac) and nag_regsn_mult_linear_upd_model (g02ddc).

Alternative solutions can be formed by imposing constraints on the arguments. If there are p arguments and the rank of the model is k , then $n_c = p - k$ constraints will have to be imposed to obtain a unique solution.

Let C be a p by n_c matrix of constraints, such that

$$C^T \beta = 0,$$

then the new parameter estimates $\hat{\beta}_c$ are given by:

$$\begin{aligned}\hat{\beta}_c &= A\hat{\beta}_{svd} \\ &= \left(I - P_0(C^T P_0)^{-1} \right) \hat{\beta}_{svd},\end{aligned}$$

where I is the identity matrix, and the variance-covariance matrix is given by:

$$AP_1D^{-2}P_1^TA^T$$

provided $(C^T P_0)^{-1}$ exists.

4 References

Golub G H and Van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

Hammarling S (1985) The singular value decomposition in multivariate statistics *SIGNUM Newslet.* **20**(3) 2–25

Searle S R (1971) *Linear Models* Wiley

5 Arguments

- 1: **ip** – Integer *Input*
On entry: the number of terms in the linear model, p .
Constraint: $\mathbf{ip} \geq 1$.
- 2: **iconst** – Integer *Input*
On entry: the number of constraints to be imposed on the arguments, n_c .
Constraint: $0 < \mathbf{iconst} < \mathbf{ip}$.
- 3: **p[ip × ip + 2 × ip]** – const double *Input*
On entry: **p** as returned by nag_regsn_mult_linear (g02dac) and nag_regsn_mult_linear_upd_model (g02ddc).
- 4: **c[ip × tdc]** – const double *Input*
Note: the (i, j) th element of the matrix C is stored in **c**[($i - 1$) \times **tdc** + $j - 1$].
On entry: the **iconst** constraints stored by column, i.e., the i th constraint is stored in the i th column of **c**.
- 5: **tdc** – Integer *Input*
On entry: the stride separating matrix column elements in the array **c**.
Constraint: $\mathbf{tdc} \geq \mathbf{iconst}$.
- 6: **b[ip]** – double *Input/Output*
On entry: the parameter estimates computed by using the singular value decomposition, $\hat{\beta}_{svd}$.
On exit: the parameter estimates of the arguments with the constraints imposed, $\hat{\beta}_c$.
- 7: **rss** – double *Input*
On entry: the residual sum of squares as returned by nag_regsn_mult_linear (g02dac) or nag_regsn_mult_linear_upd_model (g02ddc).
Constraint: $\mathbf{rss} > 0.0$.
- 8: **df** – double *Input*
On entry: the degrees of freedom associated with the residual sum of squares as returned by nag_regsn_mult_linear (g02dac) or nag_regsn_mult_linear_upd_model (g02ddc).
Constraint: $\mathbf{df} > 0.0$.
- 9: **se[ip]** – double *Output*
On exit: the standard error of the parameter estimates in **b**.
- 10: **cov[ip × (ip + 1)/2]** – double *Output*
On exit: the upper triangular part of the variance-covariance matrix of the **ip** parameter estimates given in **b**. They are stored packed by column, i.e., the covariance between the parameter estimate given in **b**[i] and the parameter estimate given in **b**[j], $j \geq i$, is stored in **cov**[$j(j + 1)/2 + i$], for $i = 0, 1, \dots, \mathbf{ip} - 1$ and $j = i, \dots, \mathbf{ip} - 1$.
- 11: **fail** – NagError * *Input/Output*
The NAG error argument (see Section 3.6 in the Essential Introduction).

6 Error Indicators and Warnings

NE_2_INT_ARG_GE

On entry, **iconst** = $\langle value \rangle$ while **ip** = $\langle value \rangle$. These arguments must satisfy **iconst** < **ip**.

NE_2_INT_ARG_LT

On entry, **tdc** = $\langle value \rangle$ while **iconst** = $\langle value \rangle$. These arguments must satisfy **tdc** ≥ **iconst**.

NE_ALLOC_FAIL

Dynamic memory allocation failed.

NE_INT_ARG_LE

On entry, **iconst** = $\langle value \rangle$.

Constraint: **iconst** > 0.

NE_INT_ARG_LT

On entry, **ip** = $\langle value \rangle$.

Constraint: **ip** ≥ 1.

NE_MAT_NOT_FULL_RANK

Matrix **c** does not give a model of full rank.

NE_REAL_ARG_LE

On entry, **df** must not be less than or equal to 0.0: **df** = $\langle value \rangle$.

On entry, **rss** must not be less than or equal to 0.0: **rss** = $\langle value \rangle$.

7 Accuracy

It should be noted that due to rounding errors an argument that should be zero when the constraints have been imposed may be returned as a value of order *machine precision*.

8 Parallelism and Performance

Not applicable.

9 Further Comments

`nag_regsn_mult_linear_tran_model` (g02dkc) is intended for use in situations in which dummy (0-1) variables have been used such as in the analysis of designed experiments when you do not wish to change the arguments of the model to give a full rank model. The function is not intended for situations in which the relationships between the independent variables are only approximate.

10 Example

Data from an experiment with four treatments and three observations per treatment are read in. A model, including the mean term, is fitted by `nag_regsn_mult_linear` (g02dac) and the results printed. The constraint that the sum of treatment effects is zero is then read in and the parameter estimates with this constraint imposed are computed by `nag_regsn_mult_linear_tran_model` (g02dkc) and printed.

10.1 Program Text

```

/* nag_regsn_mult_linear_tran_model (g02dkc) Example Program.
*
* Copyright 1991 Numerical Algorithms Group.
*
* Mark 2, 1991.
* Mark 8 revised, 2004.
*/
#include <nag.h>
#include <stdio.h>
#include <nag_stlib.h>
#include <nagg02.h>

#define X(I, J) x[(I) *tdx + J]
#define C(I, J) c[(I) *tdc + J]
#define Q(I, J) q[(I) *tdq + J]
int main(void)
{
    Integer      exit_status = 0, i, iconst, ip, j, m, n, rank, *sx = 0, tdc,
                tdq, tdx;
    double       df, rss, tol;
    double       *b = 0, *c = 0, *com_ar = 0, *cov = 0, *h = 0, *p = 0;
    double       *q = 0, *res = 0, *se = 0, *wt = 0, *wptr, *x = 0, *y = 0;
    char         nag_enum_arg[40];
    Nag_Boolean   svd, weight;
    Nag_IncludeMean mean;
    NagError      fail;

    INIT_FAIL(fail);

    printf("nag_regsn_mult_linear_tran_model (g02dkc) Example Program "
           "Results\n");
    /* Skip heading in data file */
    scanf("%*[^\n]");
    scanf("%ld %ld", &n, &m);
    scanf(" %39s", nag_enum_arg);
    /* nag_enum_name_to_value (x04nac).
     * Converts NAG enum member name to value
     */
    weight = (Nag_Boolean) nag_enum_name_to_value(nag_enum_arg);
    scanf(" %39s", nag_enum_arg);
    mean = (Nag_IncludeMean) nag_enum_name_to_value(nag_enum_arg);
    if (n >= 2 && m >= 1)
    {
        if (!(h = NAG_ALLOC(n, double)) ||
            !(res = NAG_ALLOC(n, double)) ||
            !(wt = NAG_ALLOC(n, double)) ||
            !(x = NAG_ALLOC(n*m, double)) ||
            !(y = NAG_ALLOC(n, double)) ||
            !(sx = NAG_ALLOC(m, Integer)))
        {
            printf("Allocation failure\n");
            exit_status = -1;
            goto END;
        }
        tdx = m;
    }
    else
    {
        printf("Invalid n.\n");
        exit_status = 1;
        return exit_status;
    }
    if (weight)
    {
        wptr = wt;
        for (i = 0; i < n; i++)
        {
            for (j = 0; j < m; j++)

```

```

        scanf("%lf", &X(i, j));
        scanf("%lf%lf", &y[i], &wt[i]);
    }
}
else
{
    wptr = (double *) 0;
    for (i = 0; i < n; i++)
    {
        for (j = 0; j < m; j++)
            scanf("%lf", &X(i, j));
        scanf("%lf", &y[i]);
    }
}
for (j = 0; j < m; j++)
    scanf("%ld", &sx[j]);
scanf("%ld", &ip);

if (!(b = NAG_ALLOC(ip, double)) ||
    !(c = NAG_ALLOC((ip)*(ip), double)) ||
    !(cov = NAG_ALLOC(ip*(ip+1)/2, double)) ||
    !(p = NAG_ALLOC(ip*(ip+2), double)) ||
    !(q = NAG_ALLOC(n*(ip+1), double)) ||
    !(se = NAG_ALLOC(ip, double)) ||
    !(com_ar = NAG_ALLOC(4*ip*ip+5*(ip-1), double)))
{
    printf("Allocation failure\n");
    exit_status = -1;
    goto END;
}
tdq = ip+1;
tdc = ip;

/* Set tolerance */
tol = 0.00001e0;
/* Find initial estimates using nag_regsn_mult_linear (g02dac) */
/* nag_regsn_mult_linear (g02dac).
 * Fits a general (multiple) linear regression model
 */
nag_regsn_mult_linear(mean, n, x, tdx, m, sx, ip, y, wptr,
                      &rss, &df, b, se, cov, res, h, q, tdq,
                      &svd, &rank, p, tol, com_ar, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_regsn_mult_linear (g02dac).\n%s\n",
           fail.message);
    exit_status = 1;
    goto END;
}

printf("Estimates from g02dac\n\n");
printf("Residual sum of squares = %13.4e\n", rss);
printf("Degrees of freedom = %3.1f\n\n", df);
printf("Variable Parameter estimate Standard error\n\n");
for (j = 0; j < ip; j++)
    printf("%6ld%20.4e%20.4e\n", j+1, b[j], se[j]);
printf("\n");
/*
 * Input constraints and call nag_regsn_mult_linear_tran_model (g02dkc)
 */
iconst = ip - rank;
for (i = 0; i < ip; ++i)
    for (j = 0; j < iconst; ++j)
        scanf("%lf", &c(i, j));

/* nag_regsn_mult_linear_tran_model (g02dkc).
 * Estimates of parameters of a general linear regression
 * model for given constraints
 */
nag_regsn_mult_linear_tran_model(ip, iconst, p, c, tdc, b, rss, df, se, cov,

```

```

        &fail);
if (fail.code != NE_NOERROR)
{
    printf(
        "Error from nag_regsn_mult_linear_tran_model (g02dkc).\n%s\n",
        fail.message);
    exit_status = 1;
    goto END;
}

printf("\n");
printf(
    "Estimates from nag_regsn_mult_linear_tran_model (g02dkc) using "
    "constraints\n\n");
printf("Variable      Parameter estimate      Standard error\n\n");
for (j = 0; j < ip; j++)
    printf("%6ld%20.4e%20.4e\n", j+1, b[j], se[j]);
printf("\n");

END:
NAG_FREE(h);
NAG_FREE(res);
NAG_FREE(wt);
NAG_FREE(x);
NAG_FREE(y);
NAG_FREE(sx);
NAG_FREE(b);
NAG_FREE(c);
NAG_FREE(cov);
NAG_FREE(p);
NAG_FREE(q);
NAG_FREE(se);
NAG_FREE(com_ar);

return exit_status;
}

```

10.2 Program Data

```

nag_regsn_mult_linear_tran_model (g02dkc) Example Program Data
12 4 Nag_FALSE Nag_MeanInclude
1.0 0.0 0.0 0.0 33.63
0.0 0.0 0.0 1.0 39.62
0.0 1.0 0.0 0.0 38.18
0.0 0.0 1.0 0.0 41.46
0.0 0.0 0.0 1.0 38.02
0.0 1.0 0.0 0.0 35.83
0.0 0.0 0.0 1.0 35.99
1.0 0.0 0.0 0.0 36.58
0.0 0.0 1.0 0.0 42.92
1.0 0.0 0.0 0.0 37.80
0.0 0.0 1.0 0.0 40.43
0.0 1.0 0.0 0.0 37.89
1   1   1   1   5
0.0
1.0
1.0
1.0
1.0

```

10.3 Program Results

nag_regsn_mult_linear_tran_model (g02dkc) Example Program Results
 Estimates from g02dac

Residual sum of squares = 2.2227e+01
 Degrees of freedom = 8.0

Variable	Parameter estimate	Standard error
1	3.0557e+01	3.8494e-01
2	5.4467e+00	8.3896e-01
3	6.7433e+00	8.3896e-01
4	1.1047e+01	8.3896e-01
5	7.3200e+00	8.3896e-01

Estimates from nag_regsn_mult_linear_tran_model (g02dkc) using constraints

Variable	Parameter estimate	Standard error
1	3.8196e+01	4.8117e-01
2	-2.1925e+00	8.3342e-01
3	-8.9583e-01	8.3342e-01
4	3.4075e+00	8.3342e-01
5	-3.1917e-01	8.3342e-01
