

# NAG Library Function Document

## nag\_zgbmv (f16sbc)

### 1 Purpose

nag\_zgbmv (f16sbc) performs matrix-vector multiplication for a complex band matrix.

### 2 Specification

```
#include <nag.h>
#include <nagf16.h>

void nag_zgbmv (Nag_OrderType order, Nag_TransType trans, Integer m,
                Integer n, Integer kl, Integer ku, Complex alpha, const Complex ab[],
                Integer pdab, const Complex x[], Integer incx, Complex beta,
                Complex y[], Integer incy, NagError *fail)
```

### 3 Description

nag\_zgbmv (f16sbc) performs one of the matrix-vector operations

$$y \leftarrow \alpha Ax + \beta y, \quad y \leftarrow \alpha A^T x + \beta y \quad \text{or} \quad y \leftarrow \alpha A^H x + \beta y$$

where  $A$  is an  $m$  by  $n$  complex band matrix with  $k_l$  subdiagonals and  $k_u$  superdiagonals,  $x$  and  $y$  are complex vectors, and  $\alpha$  and  $\beta$  are complex scalars.

If  $m = 0$  or  $n = 0$ , no operation is performed.

### 4 References

Basic Linear Algebra Subprograms Technical (BLAST) Forum (2001) *Basic Linear Algebra Subprograms Technical (BLAST) Forum Standard* University of Tennessee, Knoxville, Tennessee <http://www.netlib.org/blas/blast-forum/blas-report.pdf>

### 5 Arguments

1: **order** – Nag\_OrderType *Input*

*On entry:* the **order** argument specifies the two-dimensional storage scheme being used, i.e., row-major ordering or column-major ordering. C language defined storage is specified by **order** = Nag\_RowMajor. See Section 3.2.1.3 in the Essential Introduction for a more detailed explanation of the use of this argument.

*Constraint:* **order** = Nag\_RowMajor or Nag\_ColMajor.

2: **trans** – Nag\_TransType *Input*

*On entry:* specifies the operation to be performed.

**trans** = Nag\_NoTrans  
 $y \leftarrow \alpha Ax + \beta y.$

**trans** = Nag\_Trans  
 $y \leftarrow \alpha A^T x + \beta y.$

**trans** = Nag\_ConjTrans  
 $y \leftarrow \alpha A^H x + \beta y.$

*Constraint:* **trans** = Nag\_NoTrans, Nag\_Trans or Nag\_ConjTrans.

3:	<b>m</b> – Integer	<i>Input</i>
<i>On entry:</i> $m$ , the number of rows of the matrix $A$ .		
<i>Constraint:</i> $\mathbf{m} \geq 0$ .		
4:	<b>n</b> – Integer	<i>Input</i>
<i>On entry:</i> $n$ , the number of columns of the matrix $A$ .		
<i>Constraint:</i> $\mathbf{n} \geq 0$ .		
5:	<b>kl</b> – Integer	<i>Input</i>
<i>On entry:</i> $k_l$ , the number of subdiagonals within the band of $A$ .		
<i>Constraint:</i> $\mathbf{kl} \geq 0$ .		
6:	<b>ku</b> – Integer	<i>Input</i>
<i>On entry:</i> $k_u$ , the number of superdiagonals within the band of $A$ .		
<i>Constraint:</i> $\mathbf{ku} \geq 0$ .		
7:	<b>alpha</b> – Complex	<i>Input</i>
<i>On entry:</i> the scalar $\alpha$ .		
8:	<b>ab</b> [ <i>dim</i> ] – const Complex	<i>Input</i>
<b>Note:</b> the dimension, <i>dim</i> , of the array <b>ab</b> must be at least		
$\max(1, \mathbf{pdab} \times \mathbf{n})$ when <b>order</b> = Nag_ColMajor;		
$\max(1, \mathbf{m} \times \mathbf{pdab})$ when <b>order</b> = Nag_RowMajor.		
<i>On entry:</i> the $m$ by $n$ band matrix $A$ .		
This is stored as a notional two-dimensional array with row elements or column elements stored contiguously. The storage of elements $A_{ij}$ , for row $i = 1, \dots, m$ and column $j = \max(1, i - k_l), \dots, \min(n, i + k_u)$ , depends on the <b>order</b> argument as follows:		
if <b>order</b> = 'Nag_ColMajor', $A_{ij}$ is stored as <b>ab</b> [( $j - 1$ ) $\times$ <b>pdab</b> + <b>ku</b> + $i - j$ ];		
if <b>order</b> = 'Nag_RowMajor', $A_{ij}$ is stored as <b>ab</b> [( $i - 1$ ) $\times$ <b>pdab</b> + <b>kl</b> + $j - i$ ].		
9:	<b>pdab</b> – Integer	<i>Input</i>
<i>On entry:</i> the stride separating row or column elements (depending on the value of <b>order</b> ) of the matrix $A$ in the array <b>ab</b> .		
<i>Constraint:</i> $\mathbf{pdab} \geq \mathbf{kl} + \mathbf{ku} + 1$ .		
10:	<b>x</b> [ <i>dim</i> ] – const Complex	<i>Input</i>
<b>Note:</b> the dimension, <i>dim</i> , of the array <b>x</b> must be at least		
$\max(1, 1 + (\mathbf{n} - 1) \mathbf{incx} )$ when <b>trans</b> = Nag_NoTrans;		
$\max(1, 1 + (\mathbf{m} - 1) \mathbf{incx} )$ when <b>trans</b> = Nag_Trans or Nag_ConjTrans.		
<i>On entry:</i> the vector $x$ .		
11:	<b>incx</b> – Integer	<i>Input</i>
<i>On entry:</i> the increment in the subscripts of <b>x</b> between successive elements of $x$ .		
<i>Constraint:</i> $\mathbf{incx} \neq 0$ .		

12:	<b>beta</b> – Complex	<i>Input</i>
	<i>On entry:</i> the scalar $\beta$ .	
13:	<b>y</b> [ <i>dim</i> ] – Complex	<i>Input/Output</i>
	<b>Note:</b> the dimension, <i>dim</i> , of the array <b>y</b> must be at least $\max(1, 1 + (\mathbf{m} - 1) \mathbf{incy} )$ when <b>trans</b> = Nag_NoTrans; $\max(1, 1 + (\mathbf{n} - 1) \mathbf{incy} )$ when <b>trans</b> = Nag_Trans or Nag_ConjTrans.	
	<i>On entry:</i> the vector $y$ .  If <b>beta</b> = 0, <b>y</b> need not be set.  <i>On exit:</i> the updated vector $y$ .	
14:	<b>incy</b> – Integer	<i>Input</i>
	<i>On entry:</i> the increment in the subscripts of <b>y</b> between successive elements of $y$ .  <i>Constraint:</i> <b>incy</b> $\neq 0$ .	
15:	<b>fail</b> – NagError *	<i>Input/Output</i>
	The NAG error argument (see Section 3.6 in the Essential Introduction).	

## 6 Error Indicators and Warnings

### NE\_ALLOC\_FAIL

Dynamic memory allocation failed.

### NE\_BAD\_PARAM

On entry, argument  $\langle value \rangle$  had an illegal value.

### NE\_INT

On entry, **inex** =  $\langle value \rangle$ .  
*Constraint:* **inex**  $\neq 0$ .

On entry, **incy** =  $\langle value \rangle$ .  
*Constraint:* **incy**  $\neq 0$ .

On entry, **kl** =  $\langle value \rangle$ .  
*Constraint:* **kl**  $\geq 0$ .

On entry, **ku** =  $\langle value \rangle$ .  
*Constraint:* **ku**  $\geq 0$ .

On entry, **m** =  $\langle value \rangle$ .  
*Constraint:* **m**  $\geq 0$ .

On entry, **n** =  $\langle value \rangle$ .  
*Constraint:* **n**  $\geq 0$ .

### NE\_INT\_3

On entry, **pdab** =  $\langle value \rangle$ , **kl** =  $\langle value \rangle$ , **ku** =  $\langle value \rangle$ .  
*Constraint:* **pdab**  $\geq \mathbf{kl} + \mathbf{ku} + 1$ .

## 7 Accuracy

The BLAS standard requires accurate implementations which avoid unnecessary over/underflow (see Section 2.7 of Basic Linear Algebra Subprograms Technical (BLAST) Forum (2001)).

## 8 Parallelism and Performance

Not applicable.

## 9 Further Comments

None.

## 10 Example

This example computes the matrix-vector product

$$y = \alpha Ax + \beta y$$

where

$$A = \begin{pmatrix} 1.0 + 1.0i & 1.0 + 2.0i & 0.0 + 0.0i & 0.0 + 0.0i \\ 2.0 + 1.0i & 2.0 + 2.0i & 2.0 + 3.0i & 0.0 + 0.0i \\ 3.0 + 1.0i & 3.0 + 2.0i & 3.0 + 3.0i & 3.0 + 4.0i \\ 0.0 + 0.0i & 4.0 + 2.0i & 4.0 + 3.0i & 4.0 + 4.0i \\ 0.0 + 0.0i & 0.0 + 0.0i & 5.0 + 3.0i & 5.0 + 4.0i \\ 0.0 + 0.0i & 0.0 + 0.0i & 0.0 + 0.0i & 6.0 + 4.0i \end{pmatrix},$$

$$x = \begin{pmatrix} 1.0 - 1.0i \\ 2.0 - 2.0i \\ 3.0 - 3.0i \\ 4.0 - 4.0i \end{pmatrix},$$

$$y = \begin{pmatrix} -3.5 + 0.0i \\ -11.5 + 1.0i \\ -27.5 + 3.0i \\ -29.0 + 7.5i \\ -25.5 + 10.0i \\ -14.5 + 10.0i \end{pmatrix},$$

$$\alpha = 1.0 + 0.0i \quad \text{and} \quad \beta = 2.0 + 0.0i.$$

### 10.1 Program Text

```
/* nag_zgbmv (f16sbc) Example Program.
*
* Copyright 2005 Numerical Algorithms Group.
*
* Mark 8, 2005.
*/
#include <stdio.h>
#include <nag.h>
#include <nag_stdl�.h>
#include <nagf16.h>

int main(void)
{
    /* Scalars */
    Complex alpha, beta;
    Integer ab_size, exit_status, i, incx, incy, j, kl, ku,
    m, n, pdab, xlen, ylen;

    /* Arrays */
    Complex *ab = 0, *x = 0, *y = 0;
    char nag_enum_arg[40];

    /* Nag Types */
}
```

```

NagError      fail;
Nag_OrderType order;
Nag_TransType trans;

#ifndef NAG_COLUMN_MAJOR
#define AB(I, J) ab[(J-1)*pdab + ku + I - J]
    order = Nag_ColMajor;
#else
#define AB(I, J) ab[(I-1)*pdab + kl + J - I]
    order = Nag_RowMajor;
#endif

exit_status = 0;
INIT_FAIL(fail);

printf("nag_zgbmv (f16sbc) Example Program Results\n\n");

/* Skip heading in data file */
scanf("%*[^\n] ");

/* Read the problem dimensions */
scanf("%ld%ld%ld%ld%*[^\n] ",
      &m, &n, &kl, &ku);
/* Read the transpose parameter */
scanf("%39s%*[^\n] ", nag_enum_arg);
/* nag_enum_name_to_value (x04nac).
 * Converts NAG enum member name to value
 */
trans = (Nag_TransType) nag_enum_name_to_value(nag_enum_arg);
/* Read scalar parameters */
scanf(" ( %lf, %lf ) ( %lf, %lf )%*[^\n] ",
      &alpha.re, &alpha.im, &beta.re, &beta.im);
/* Read increment parameters */
scanf("%ld%ld%*[^\n] ", &incx, &incy);

pdab = kl + ku + 1;
#ifndef NAG_COLUMN_MAJOR
    ab_size = pdab*n;
#else
    ab_size = pdab*m;
#endif

if (trans == Nag_NoTrans)
{
    xlabel = MAX(1, 1 + (n - 1)*ABS(incx));
    ylabel = MAX(1, 1 + (m - 1)*ABS(incy));
}
else
{
    xlabel = MAX(1, 1 + (m - 1)*ABS(incx));
    ylabel = MAX(1, 1 + (n - 1)*ABS(incy));
}

if (m > 0 && n > 0)
{
    /* Allocate memory */
    if (!(ab = NAG_ALLOC(ab_size, Complex)) ||
        !(x = NAG_ALLOC(xlabel, Complex)) ||
        !(y = NAG_ALLOC(ylabel, Complex)))
    {
        printf("Allocation failure\n");
        exit_status = -1;
        goto END;
    }
}
else
{
    printf("Invalid m or n\n");
    exit_status = 1;
    return exit_status;
}

```

```

/* Input matrix A and vectors x and y */

for (i = 1; i <= m; ++i)
{
    for (j = MAX(1, i-kl); j <= MIN(n, i+ku); ++j)
        scanf(" (% lf , %lf )", &AB(i, j).re, &AB(i, j).im);
    scanf("%*[^\n] ");
}
for (i = 1; i <= xlen; ++i)
    scanf(" (% lf , %lf )%*[^\n] ", &x[i - 1].re, &x[i - 1].im);
for (i = 1; i <= ylen; ++i)
    scanf(" (% lf , %lf )%*[^\n] ", &y[i - 1].re, &y[i - 1].im);

/* nag_zgbmv (f16sbc).
 * Complex valued band matrix-vector multiply.
 */
nag_zgbmv(order, trans, m, n, kl, ku, alpha, ab, pdab, x,
           incx, beta, y, incy, &fail);
if (fail.code != NE_NOERROR)
{
    printf("Error from nag_zgbmv.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

/* Print output vector y */
printf("%s\n", " y");
for (i = 1; i <= ylen; ++i)
{
    printf("(%.11f,%.11f)\n", y[i-1].re, y[i-1].im);
}

END:
NAG_FREE(ab);
NAG_FREE(x);
NAG_FREE(y);

return exit_status;
}

```

## 10.2 Program Data

```

nag_zgbmv (f16sbc) Example Program Data
 6 4 2 1                               :Values of m, n, kl, ku
Nag_NoTrans                            : trans
( 1.0, 0.0) ( 2.0, 0.0)                : alpha, beta
 1 1                                     : incx, incy
( 1.0, 1.0) ( 1.0, 2.0)
( 2.0, 1.0) ( 2.0, 2.0) ( 2.0, 3.0)
( 3.0, 1.0) ( 3.0, 2.0) ( 3.0, 3.0) ( 3.0, 4.0)
          ( 4.0, 2.0) ( 4.0, 3.0) ( 4.0, 4.0)
          ( 5.0, 3.0) ( 5.0, 4.0)
          ( 6.0, 4.0)   : the end of matrix A
( 1.0,-1.0)
( 2.0,-2.0)
( 3.0,-3.0)
( 4.0,-4.0)                           : the end of vector x
(-3.5, 0.0)
(-11.5, 1.0)
(-27.5, 3.0)
(-29.0, 7.5)
(-25.5, 10.0)
(-14.5, 10.0)                         : the end of vector y

```

### 10.3 Program Results

```
nag_zgbmv (f16sbc) Example Program Results
```

```
Y
( 1.000000, 2.000000)
( 3.000000, 4.000000)
( 5.000000, 6.000000)
( 7.000000, 8.000000)
( 9.000000, 10.000000)
( 11.000000, 12.000000)
```

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